

8

FIG. 1

FIG. 2

30

2/7

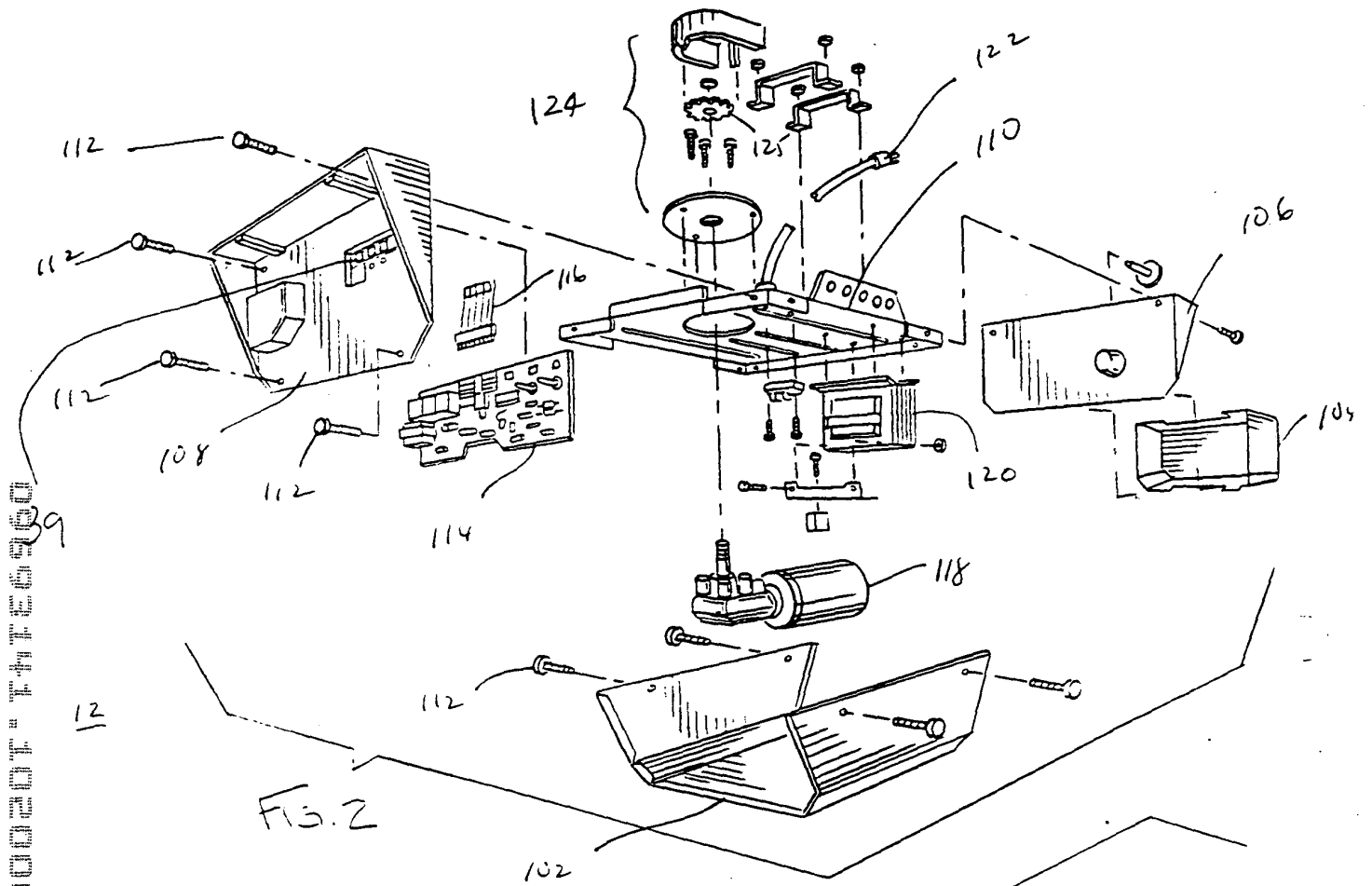


FIG. 2

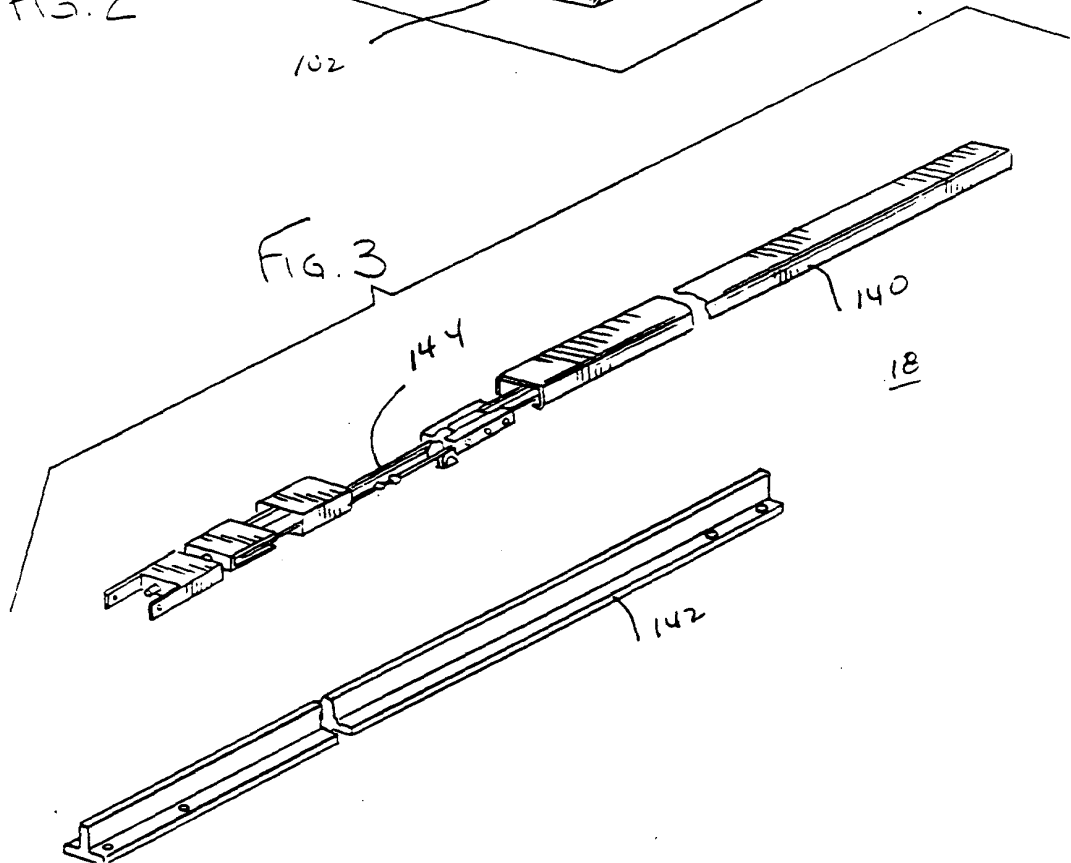


FIG. 3

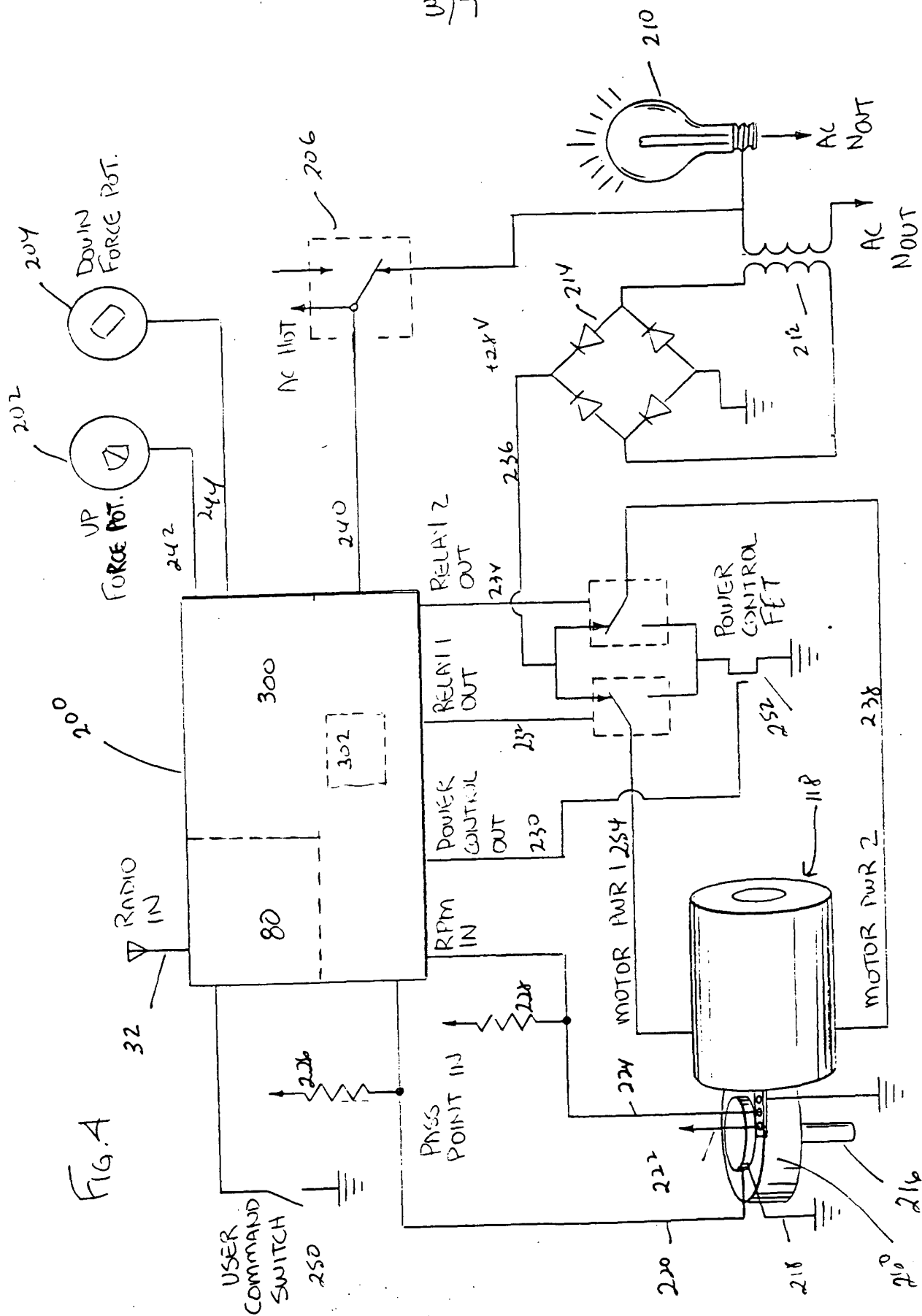
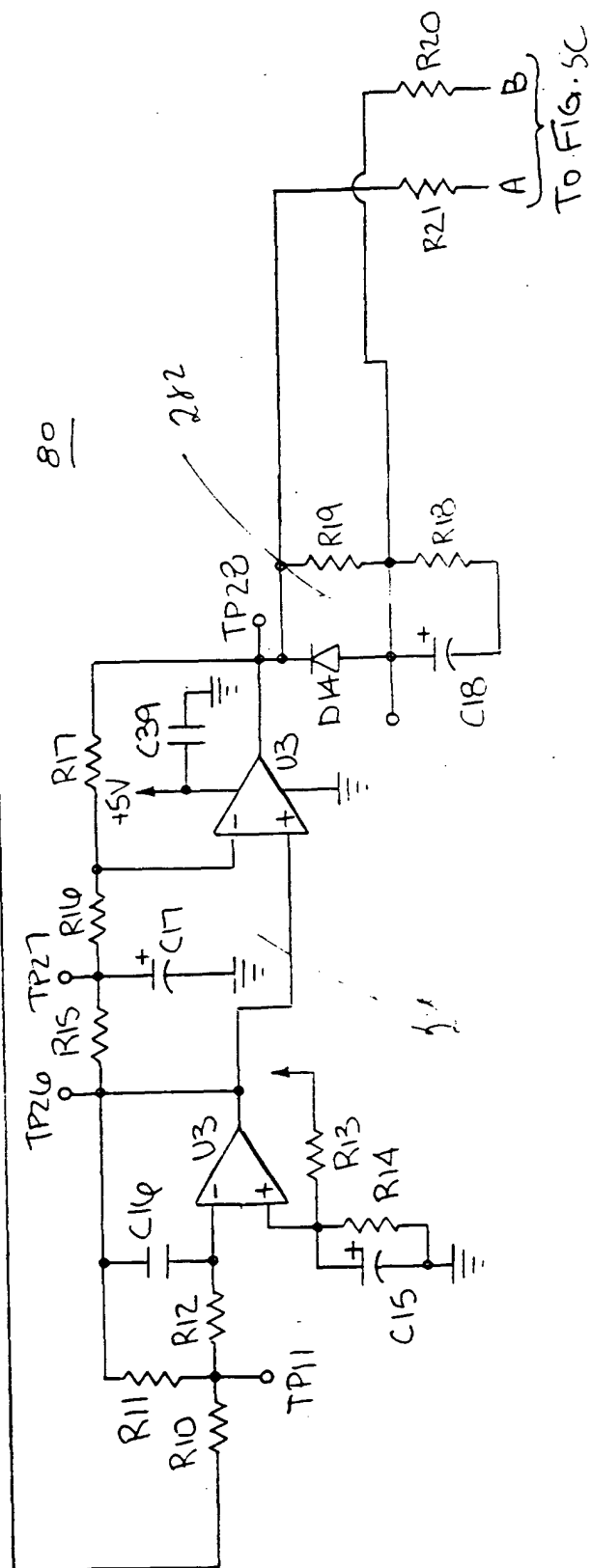
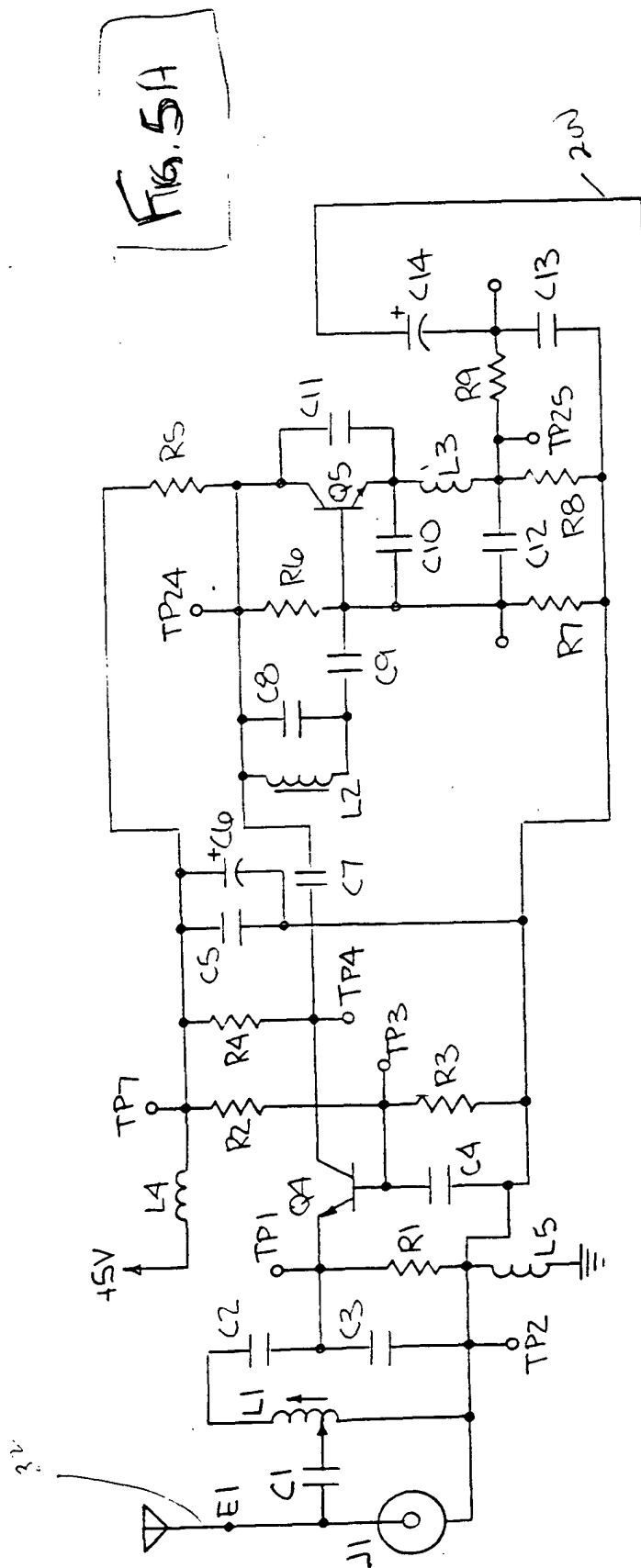


FIG. A



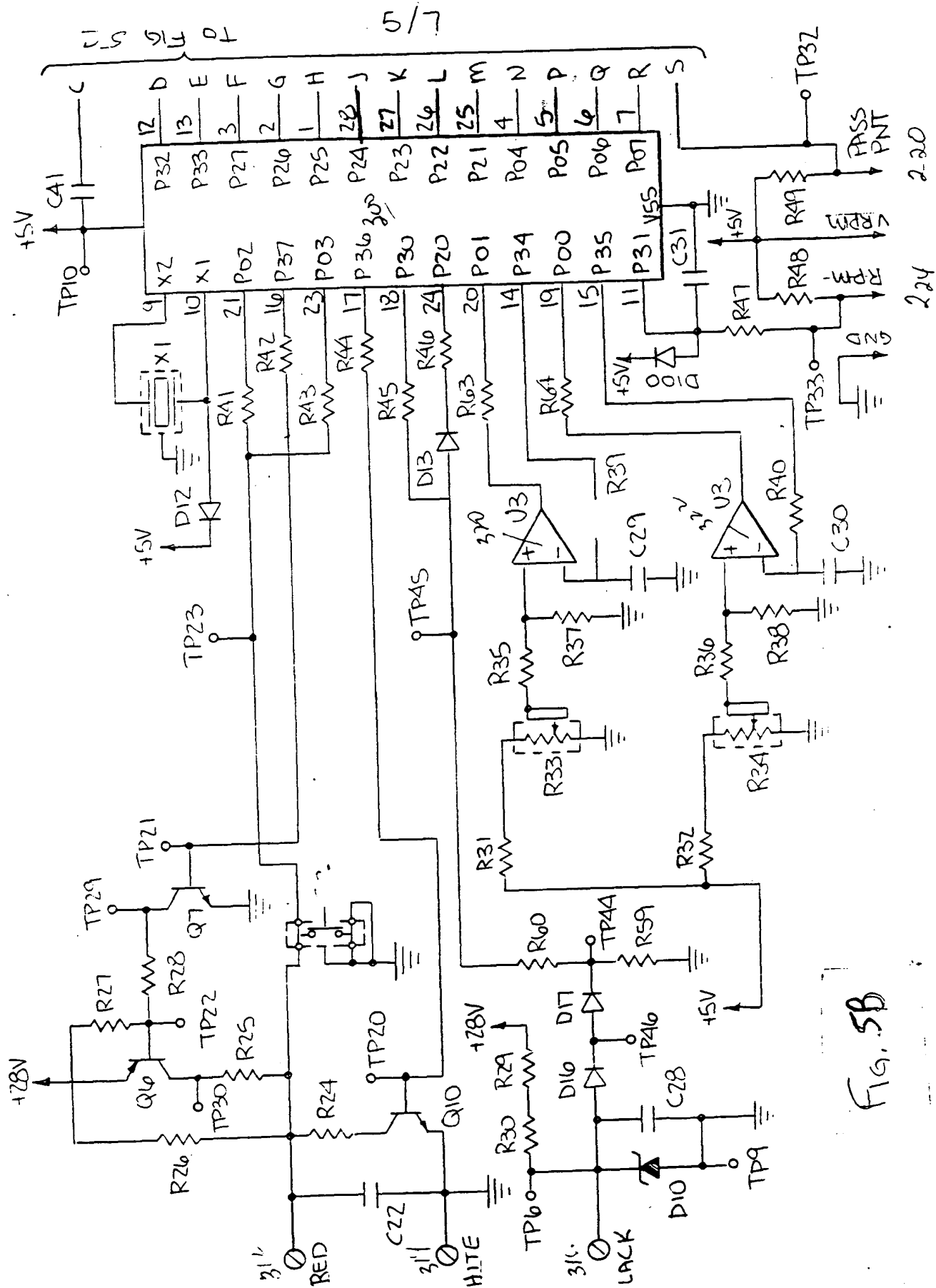
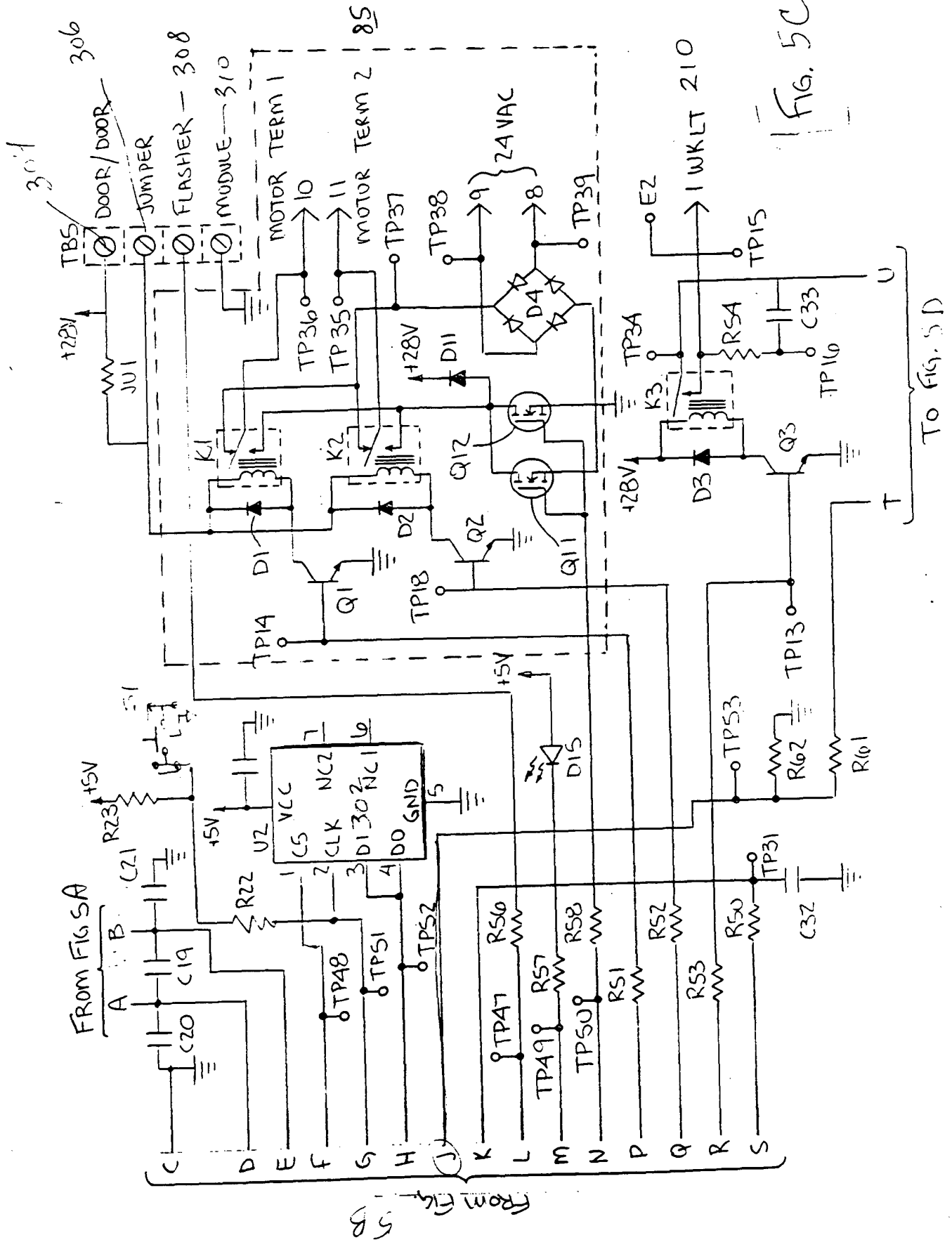


Fig. 5B



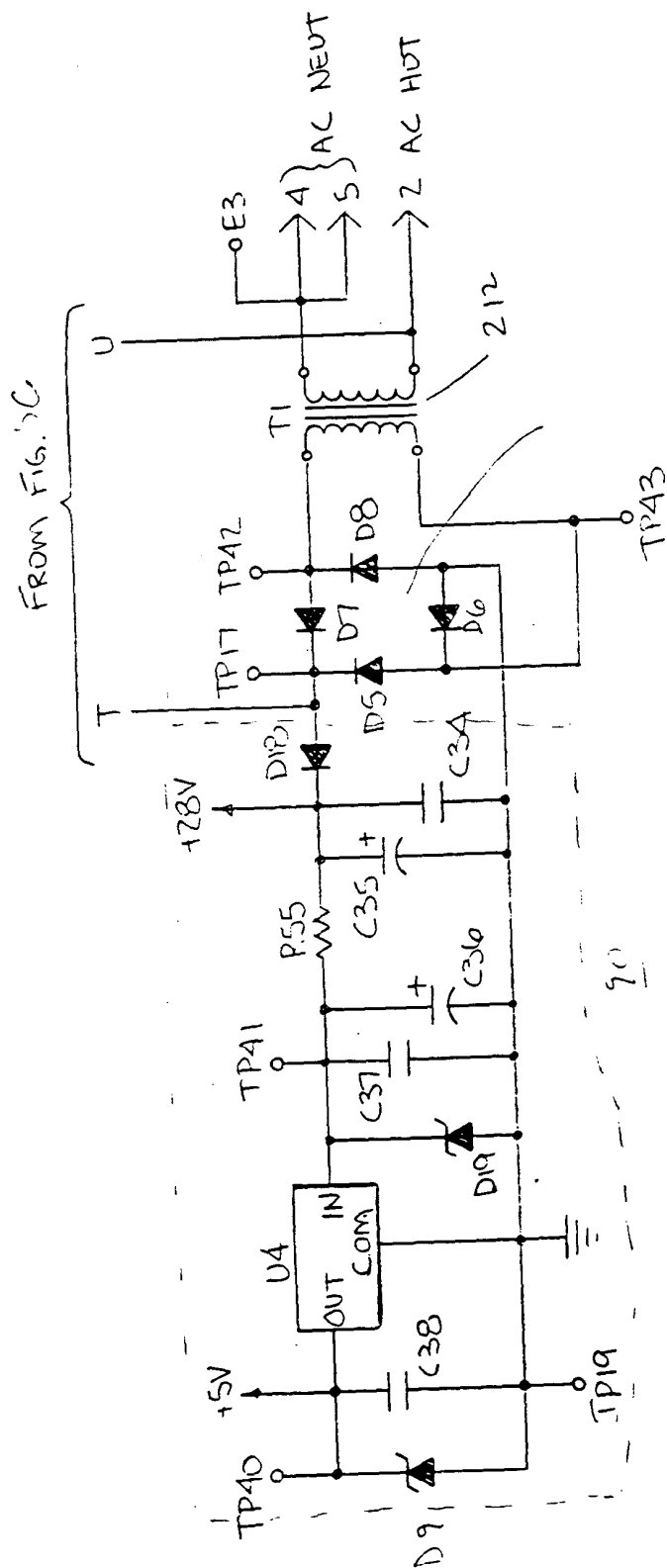
[illegible]
$$\frac{\square}{r/r}$$


Fig. 5D

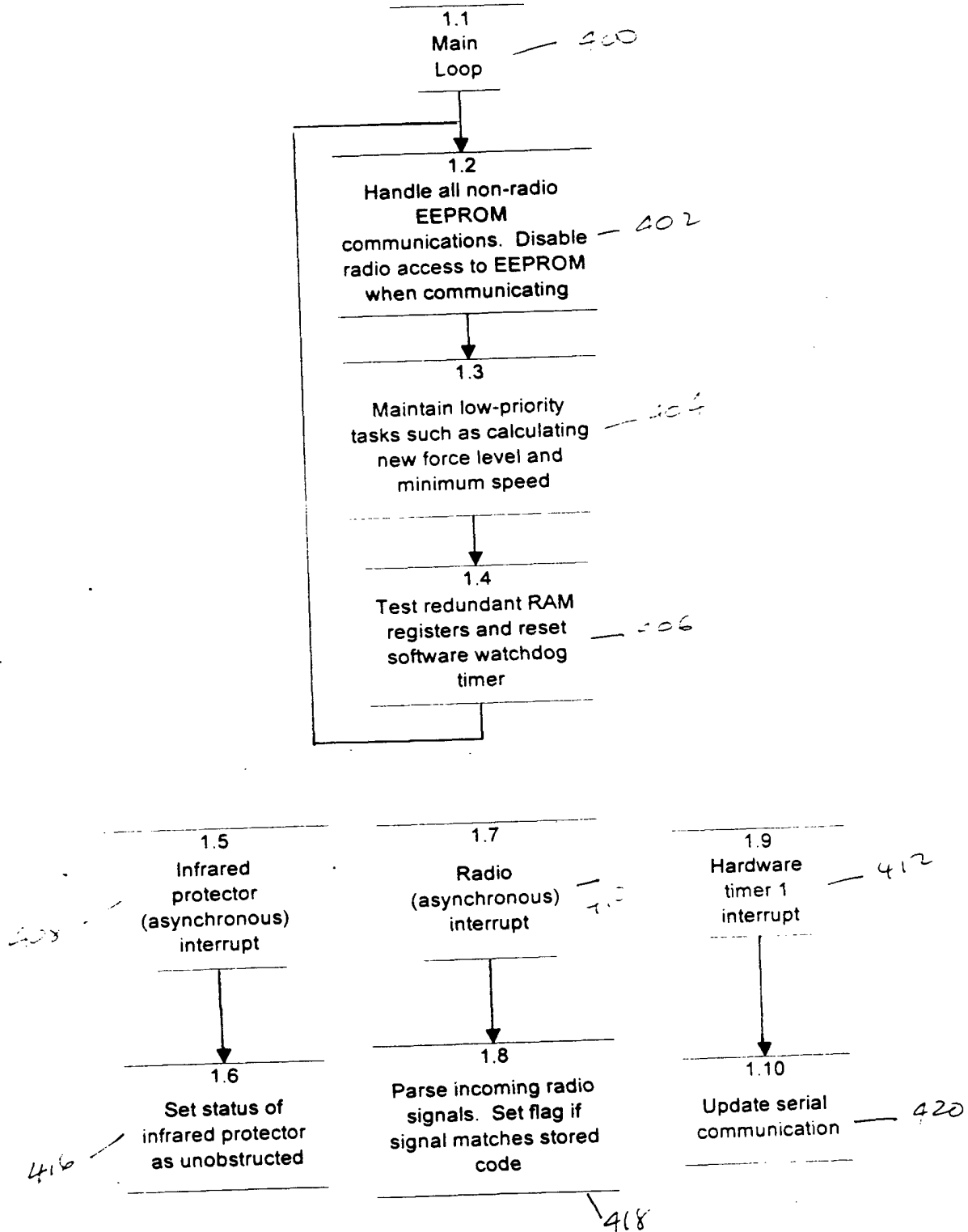


Fig. 6A

1.11 Hardware timer 0 interrupt

1.12
Read incoming AC
line signal and
handle motor phase
control output

1.13

Task switch the following tasks:

1.14

Update software
timers

1.15

Debounce wall control switches

1.16

Control motor state,
including relay
outputs and motor
safety systems.

1.17

RPM
(asynchronous)
interrupt

1.18

Calculate motor
RPM period

1.19

Update position
of door

Fig. 6E

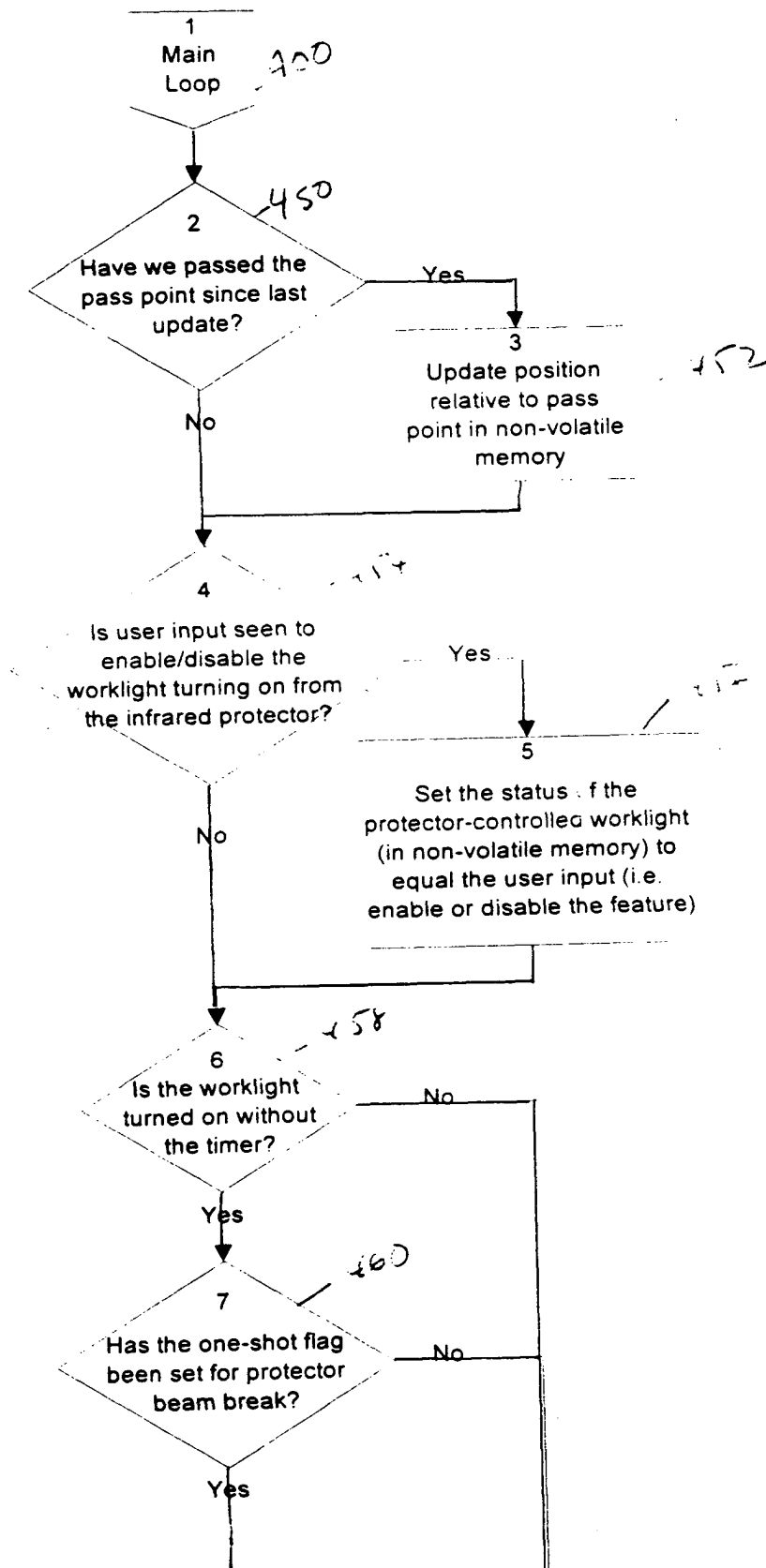


Fig. 7A

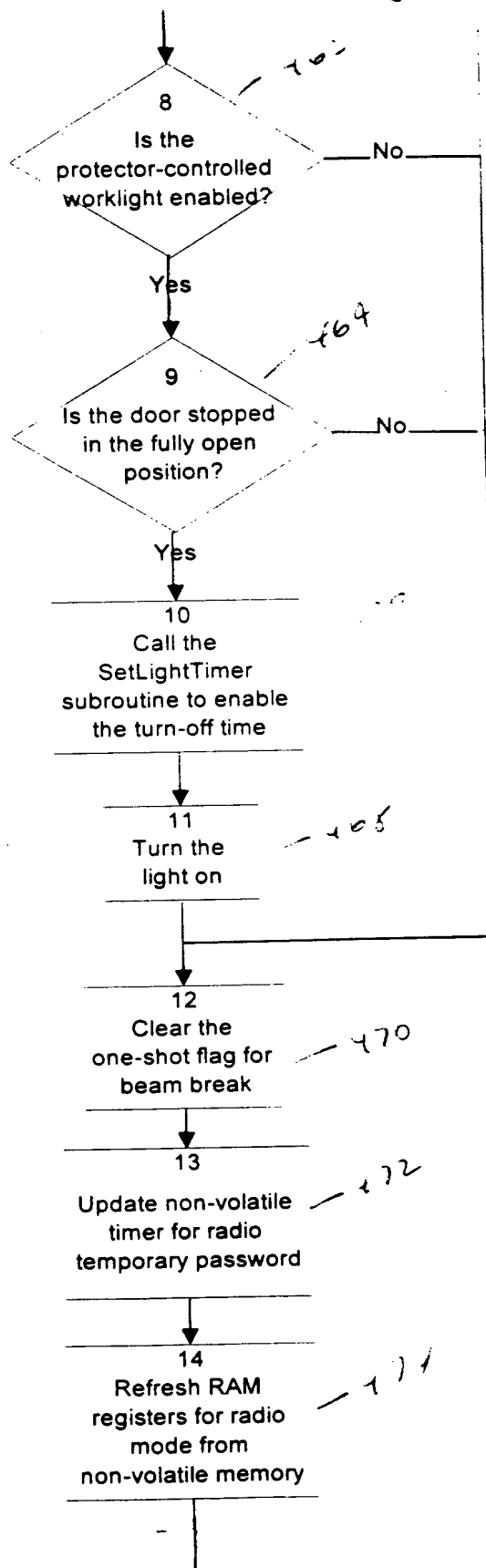


Fig. 7B

000201-14166960

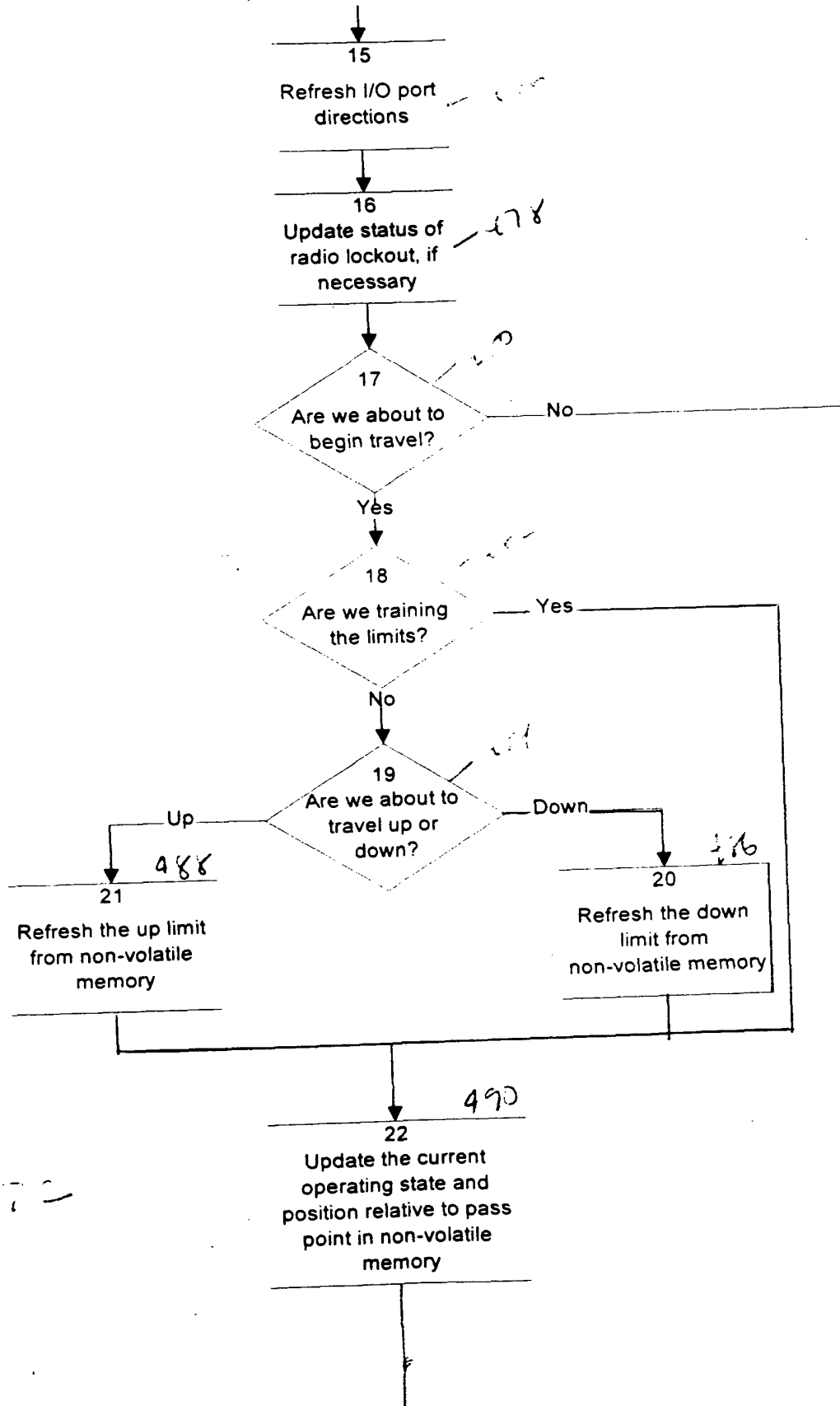


Fig. 7c

000201" TFE6960

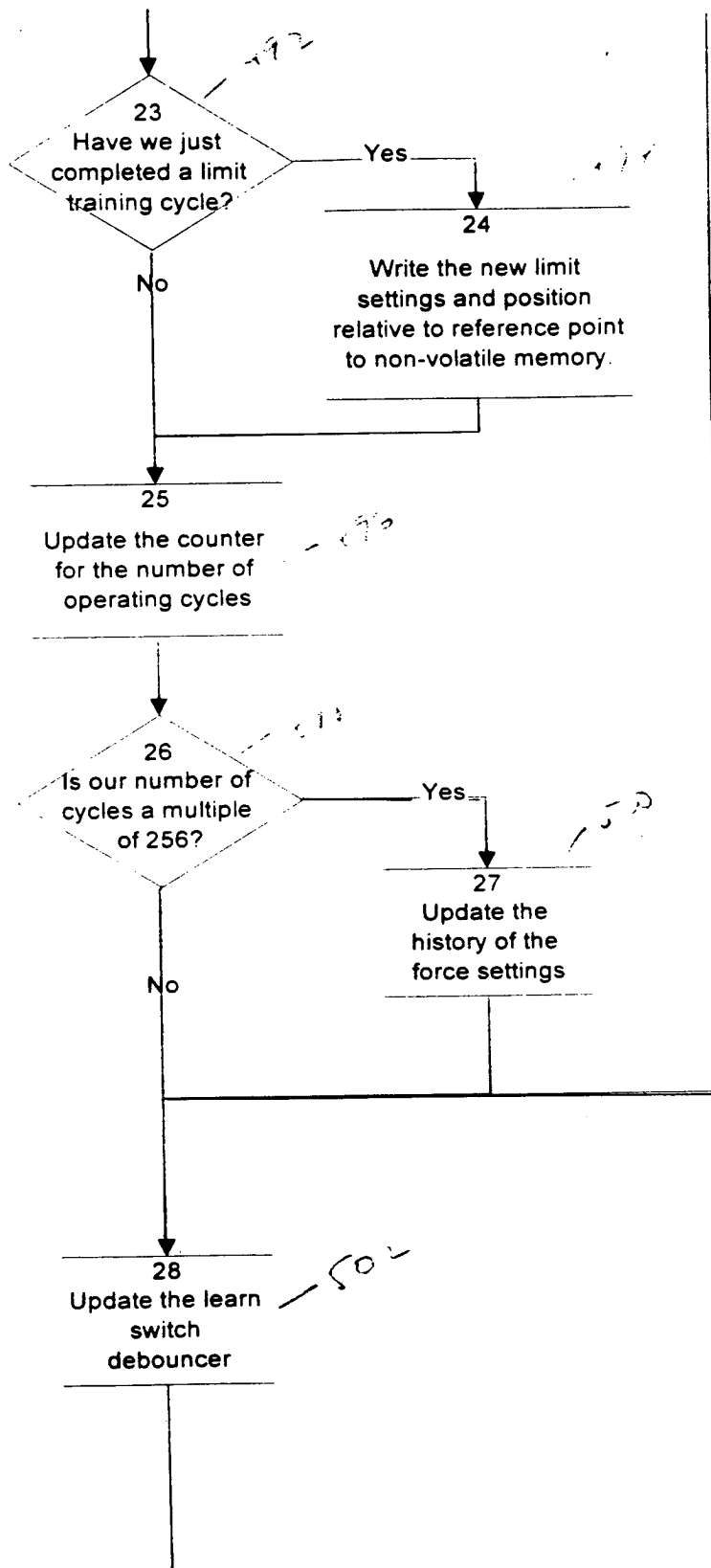


Fig. 7D

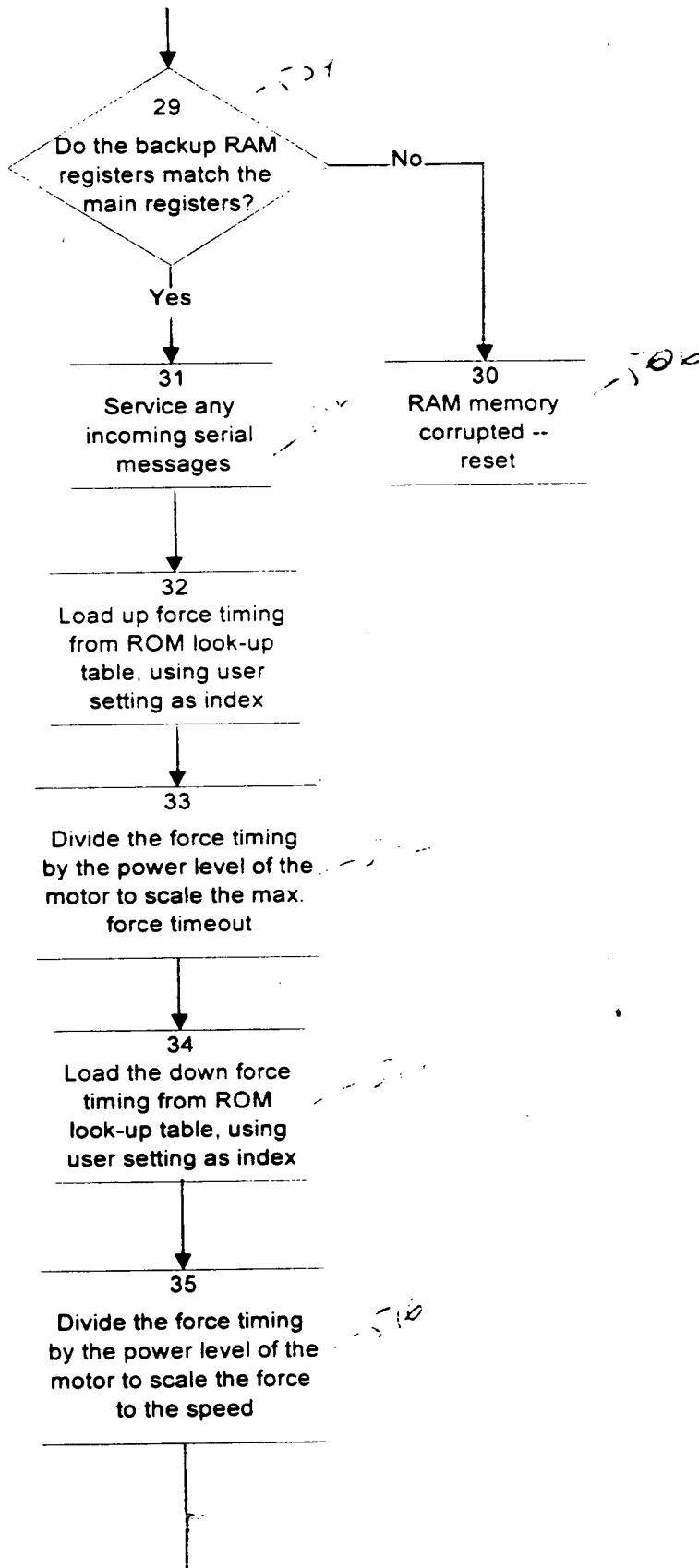


Fig. 7E

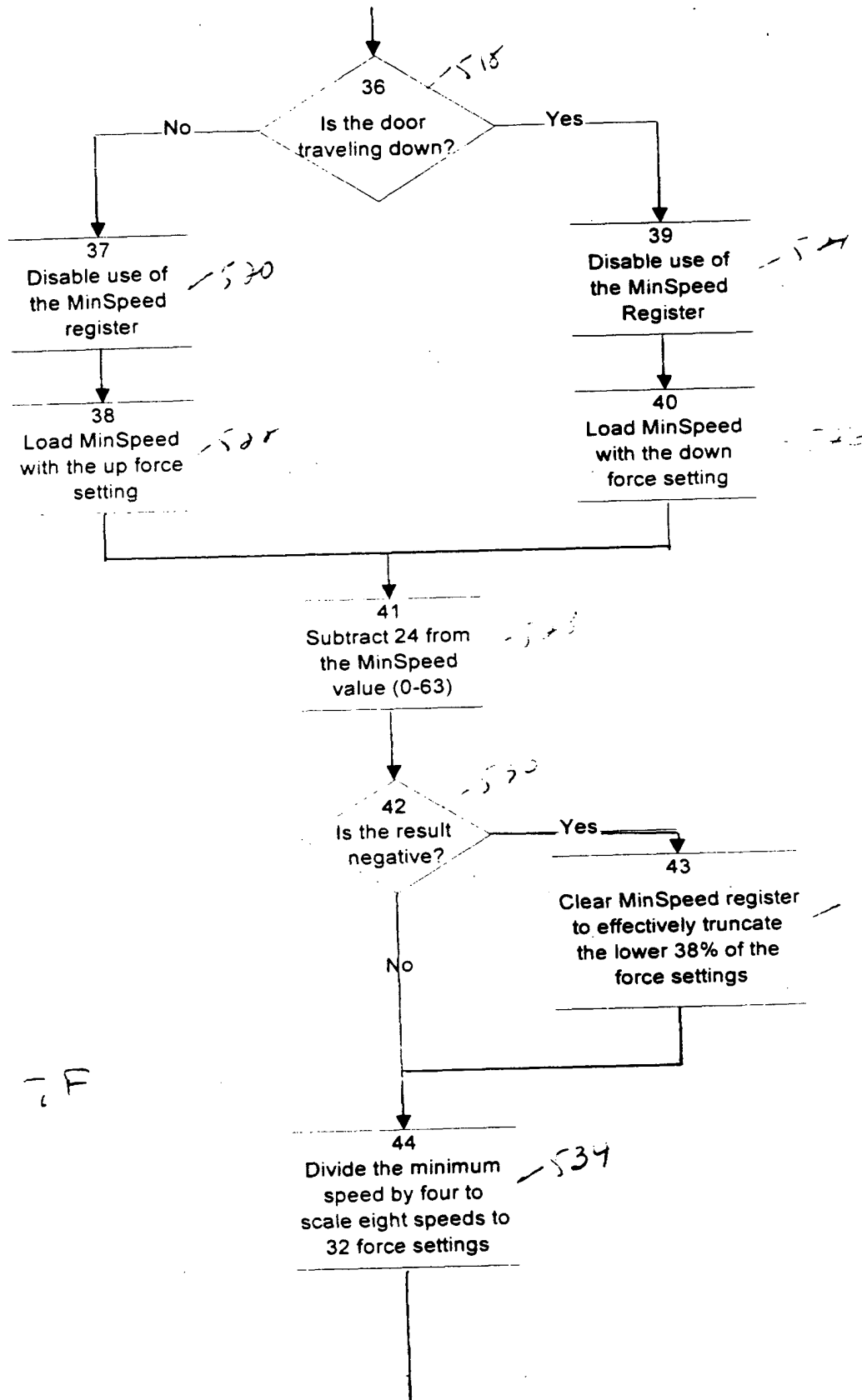


Fig. 2F

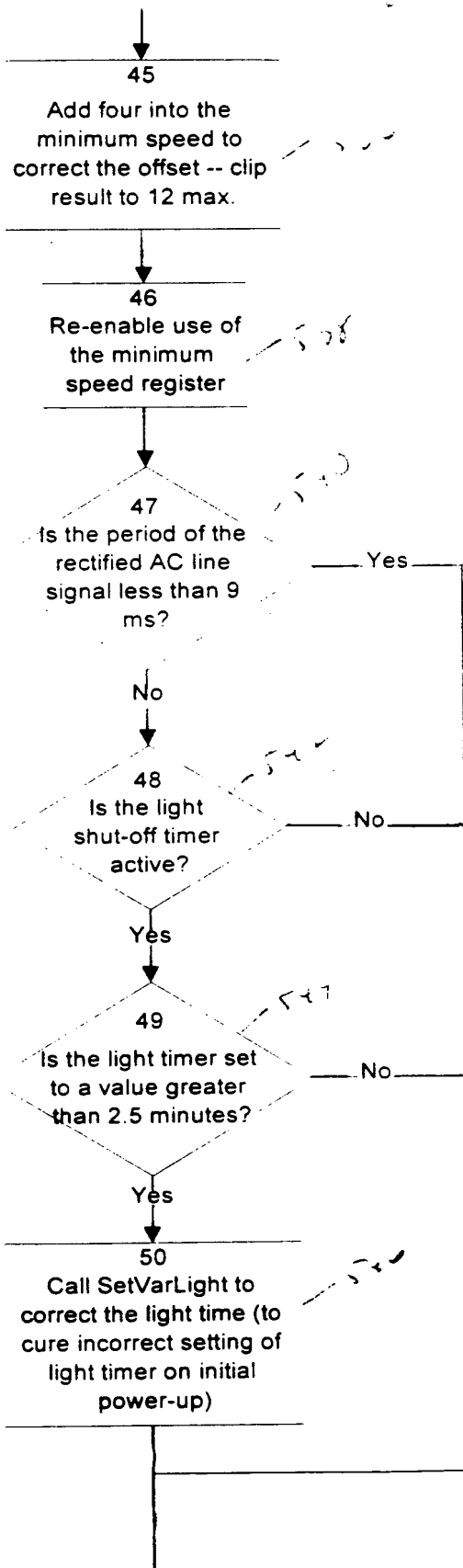


Fig 74

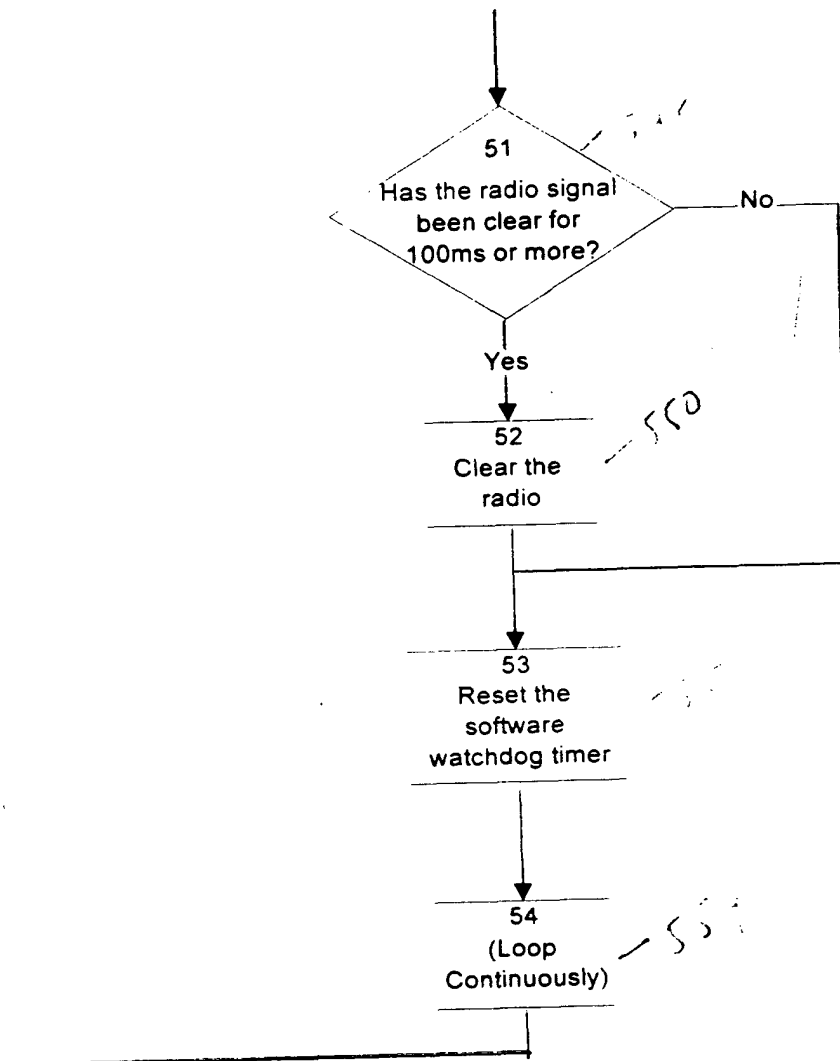


Fig. 7 H

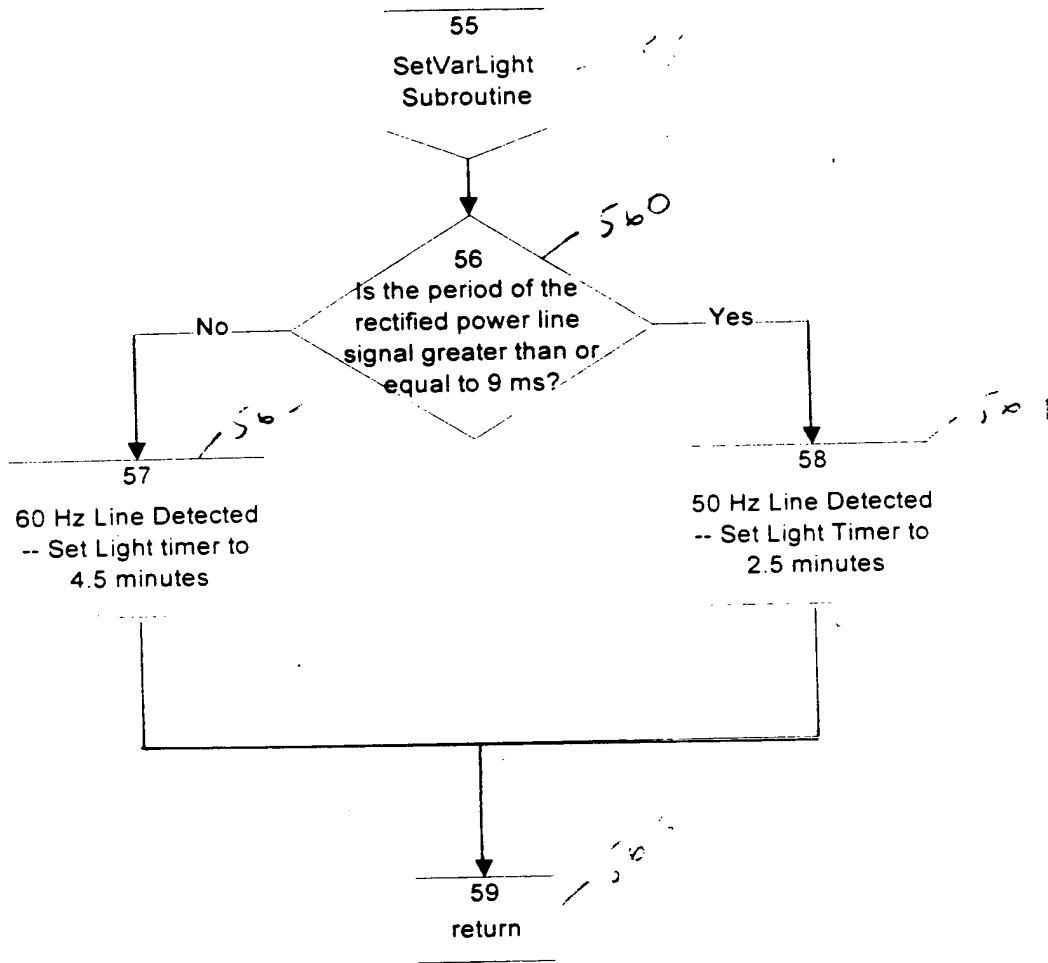


Fig. 8

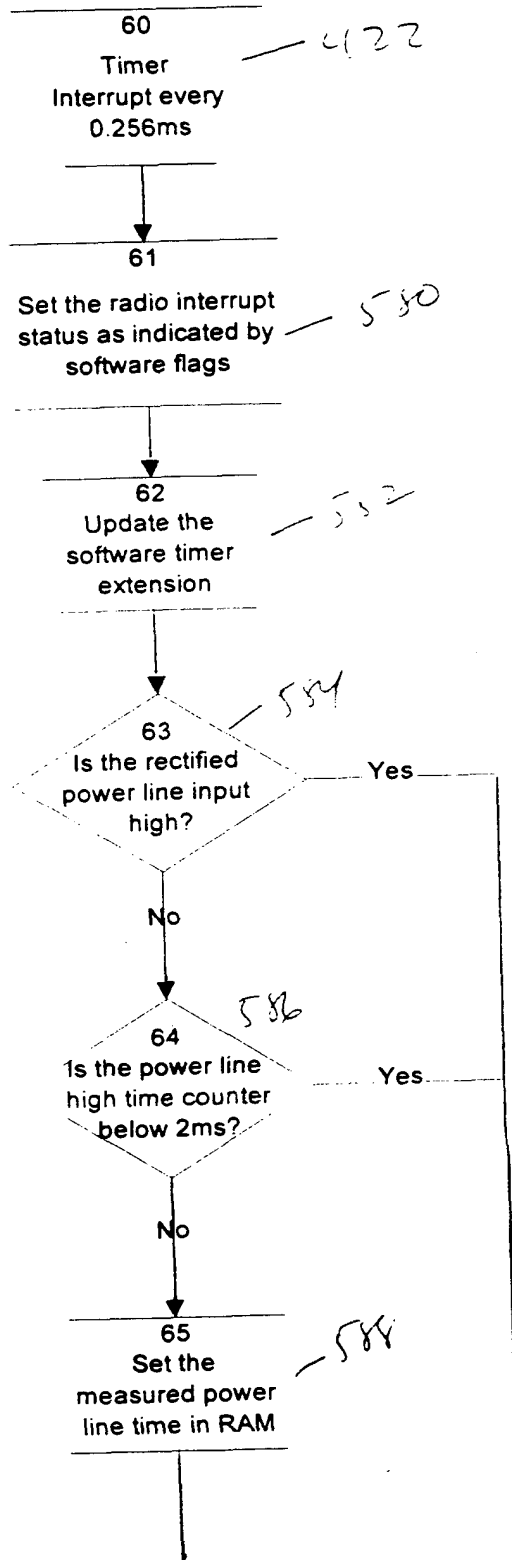


Fig. 9A

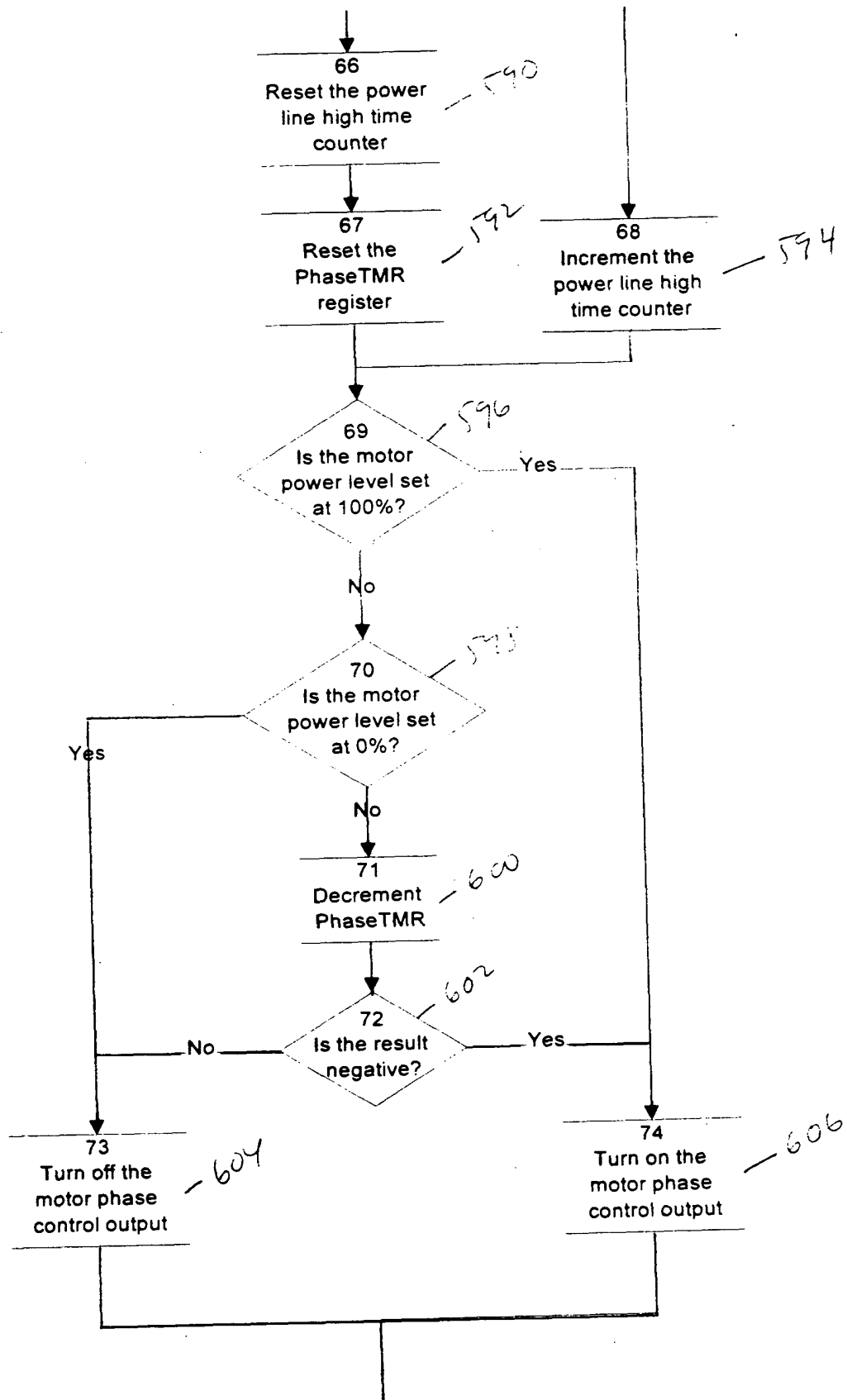


Fig. 9B

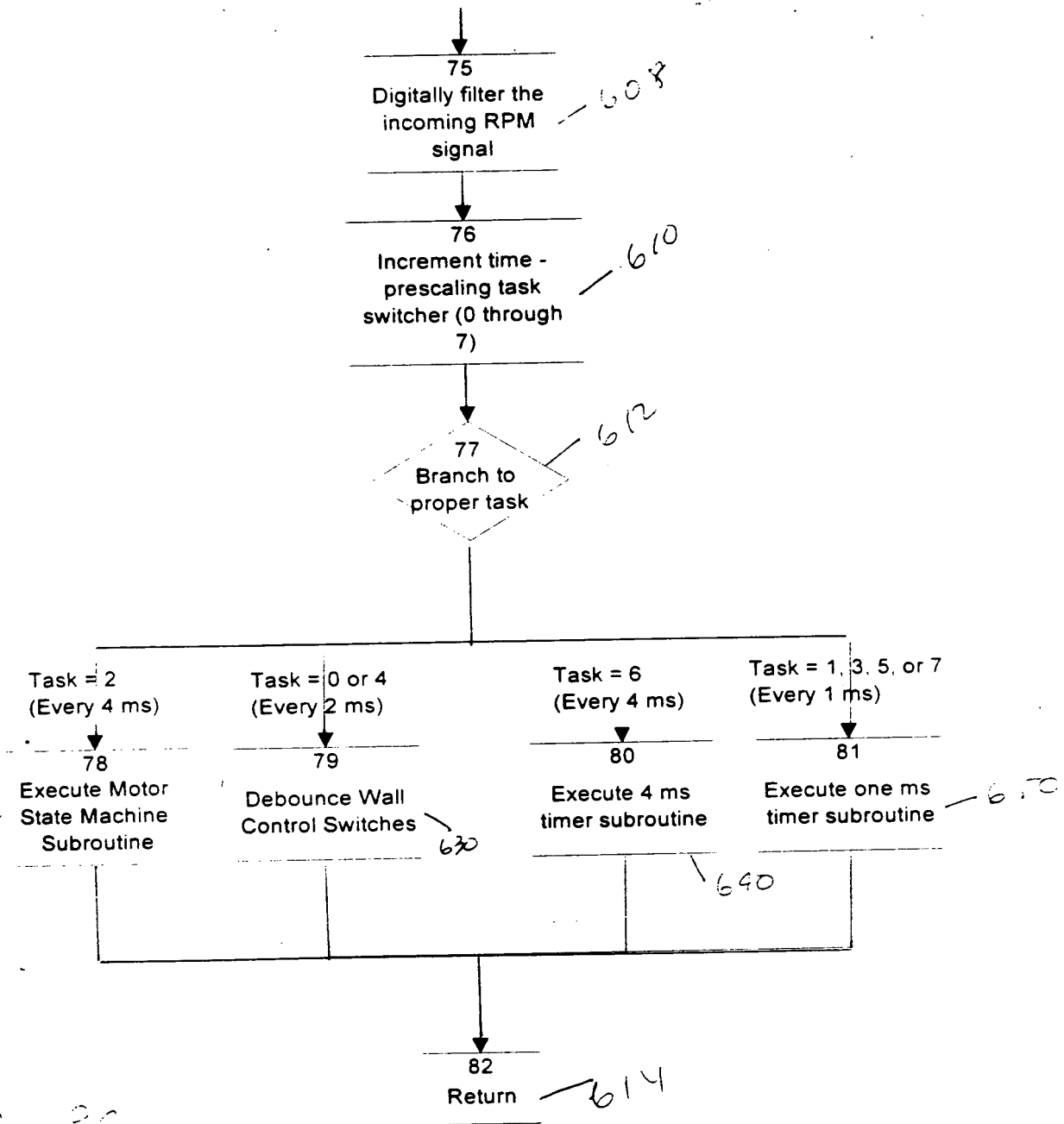


Fig. 2c

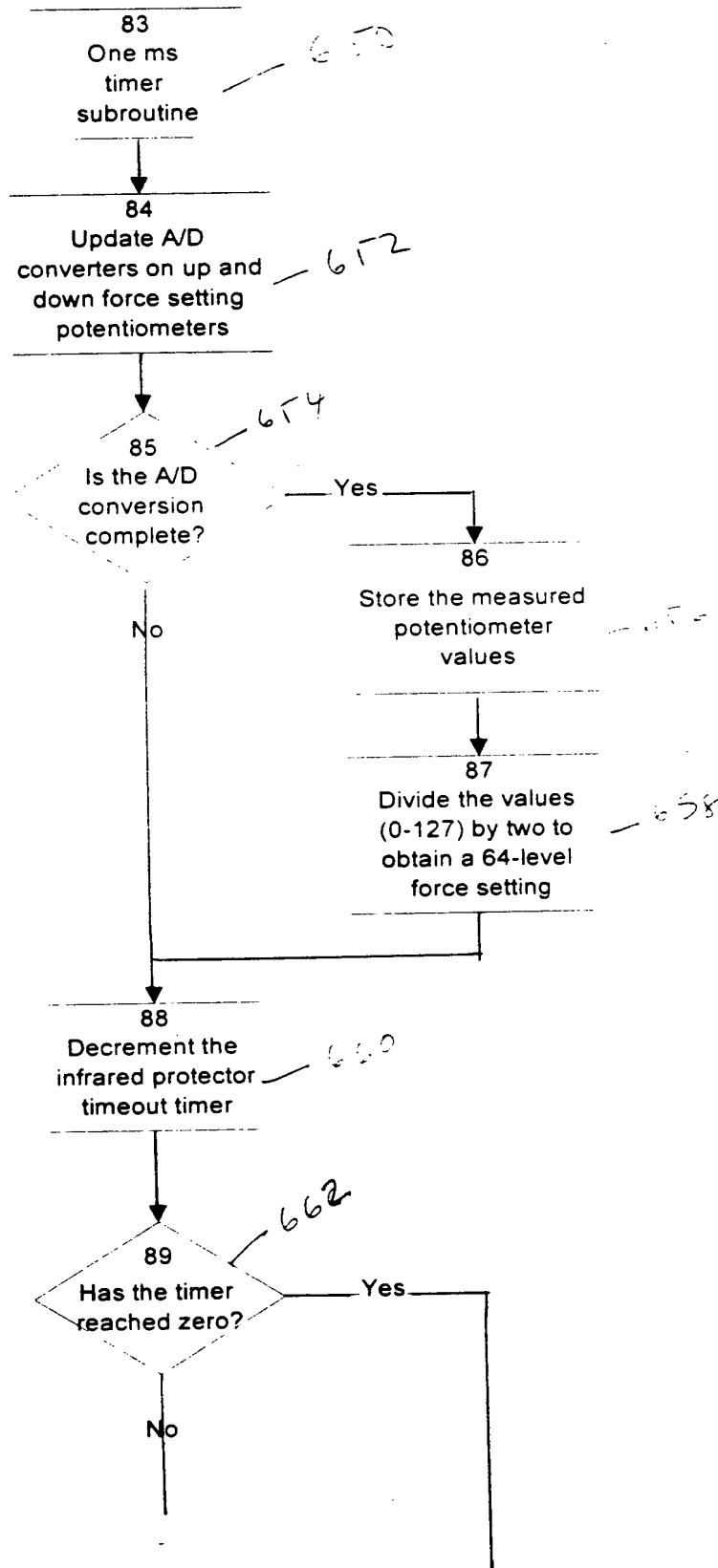


Fig. 10A

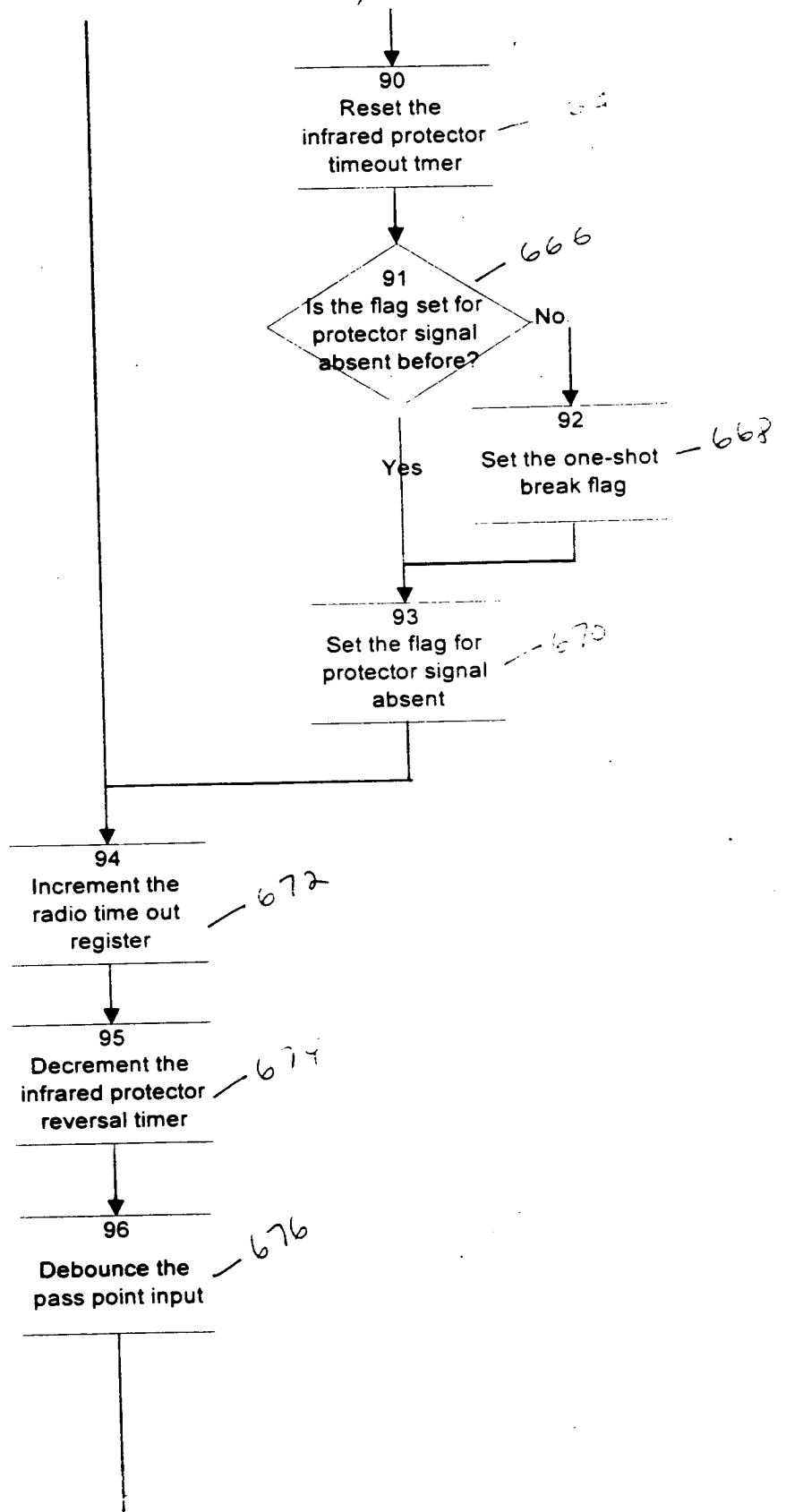


Fig. 10B

000207 THE 6950

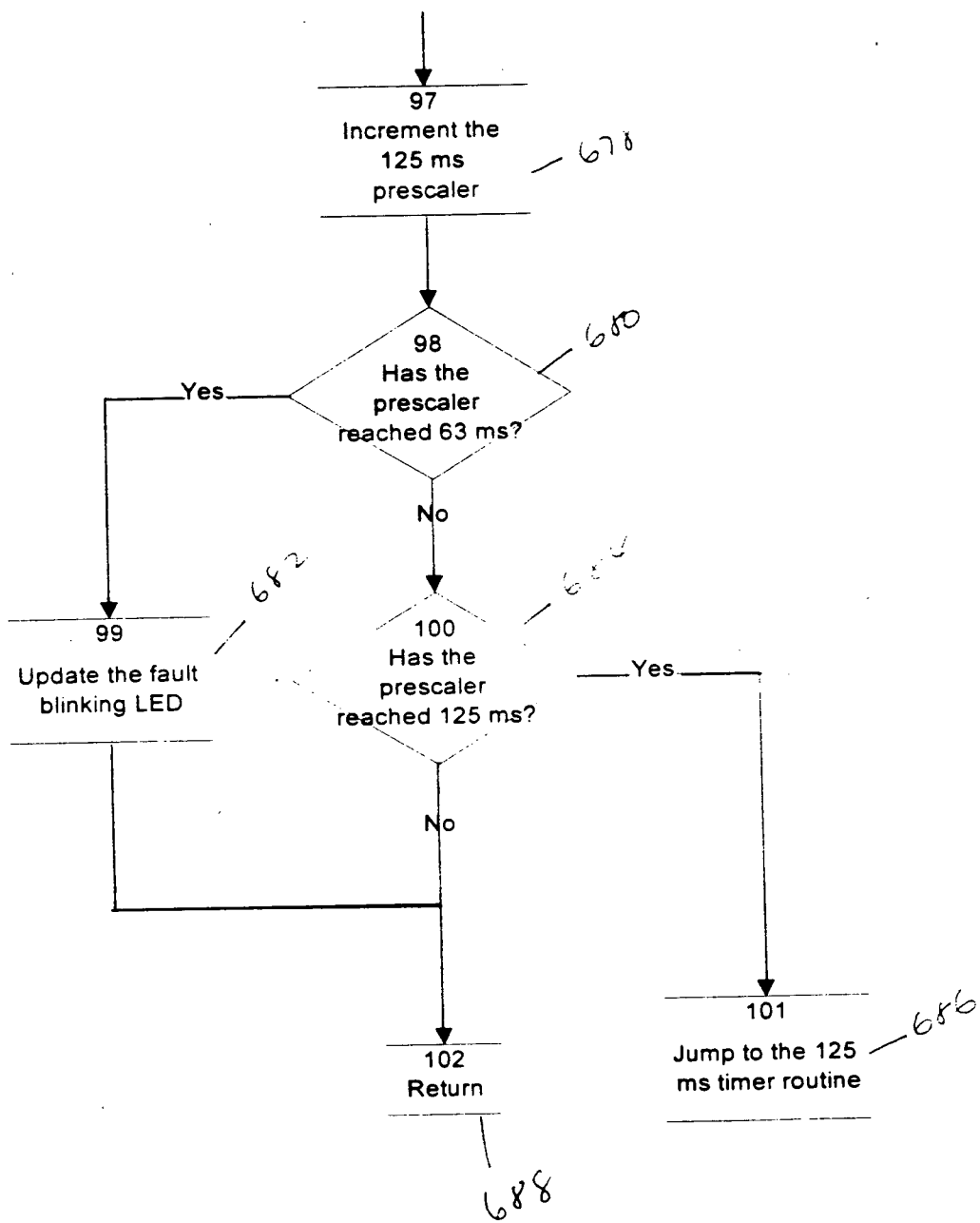
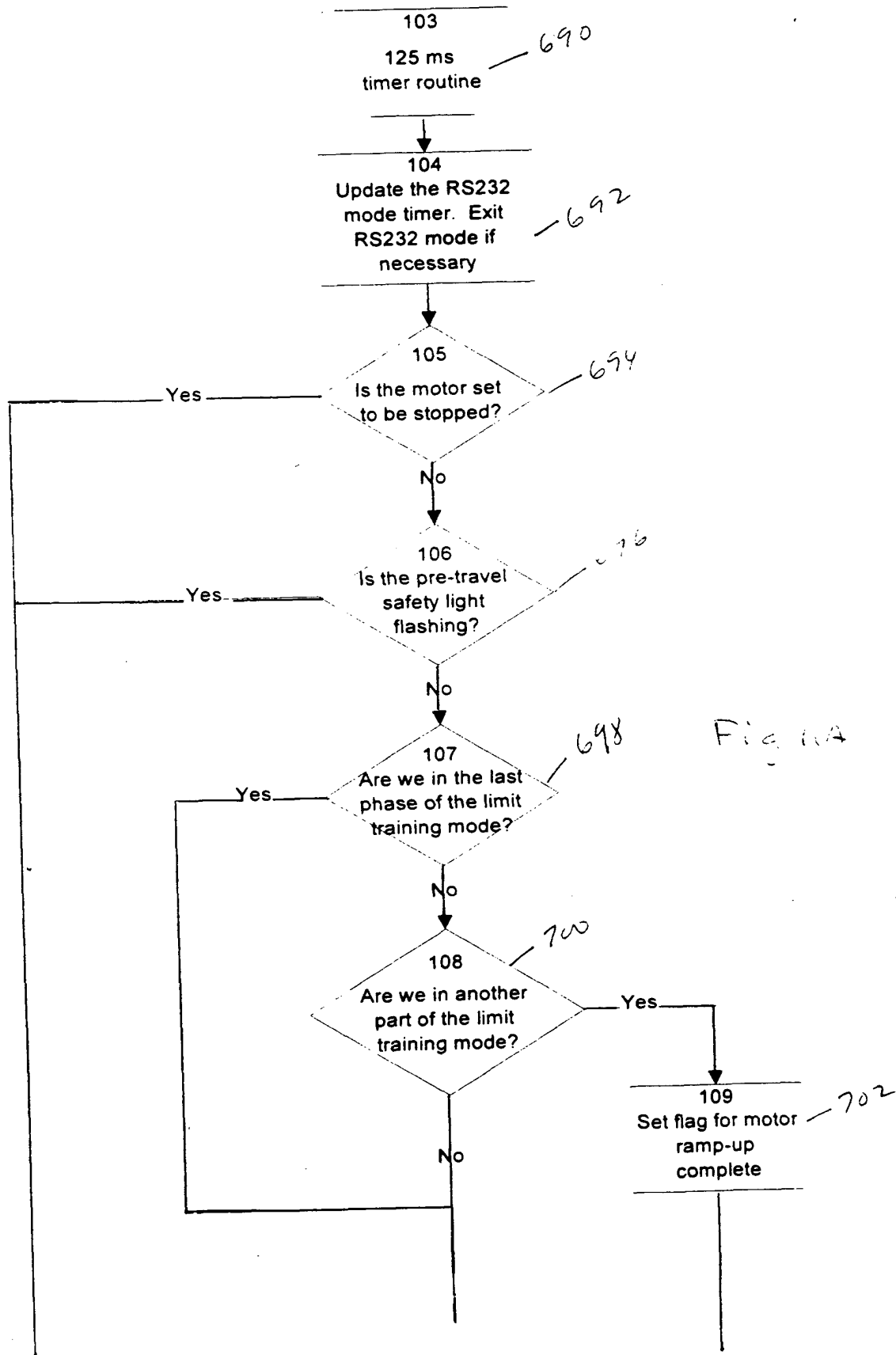
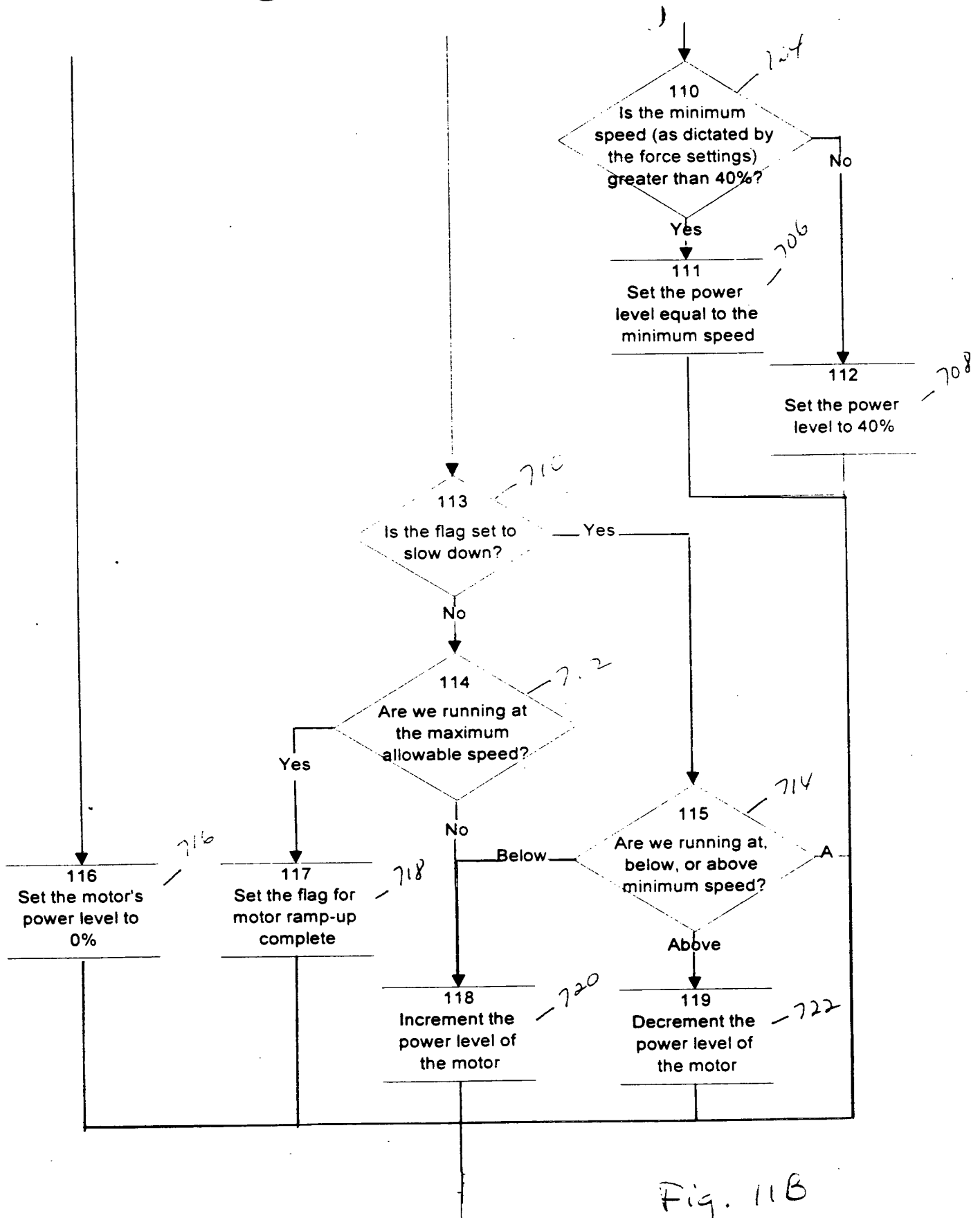


Fig. 10C

000201" T4E6960





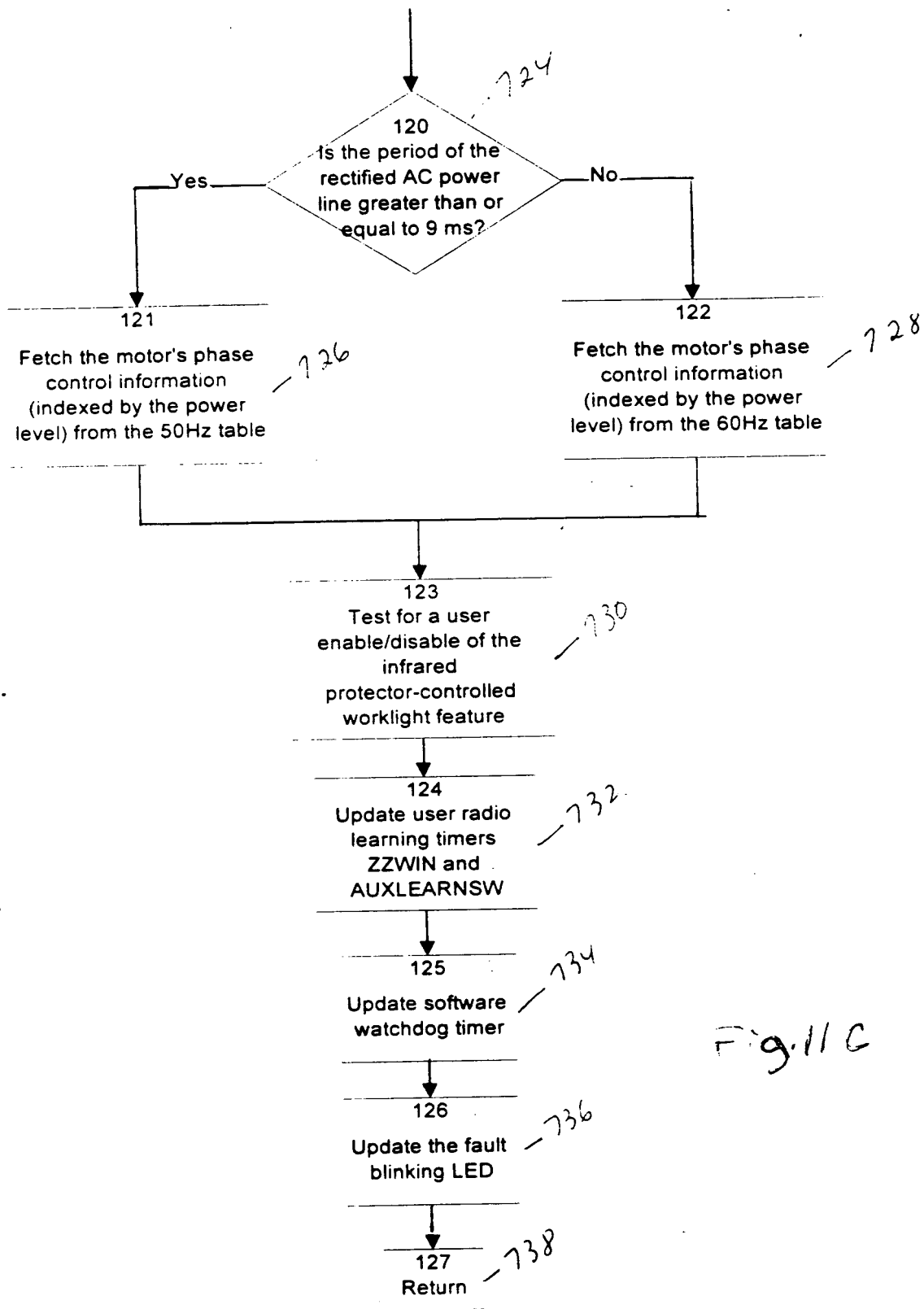
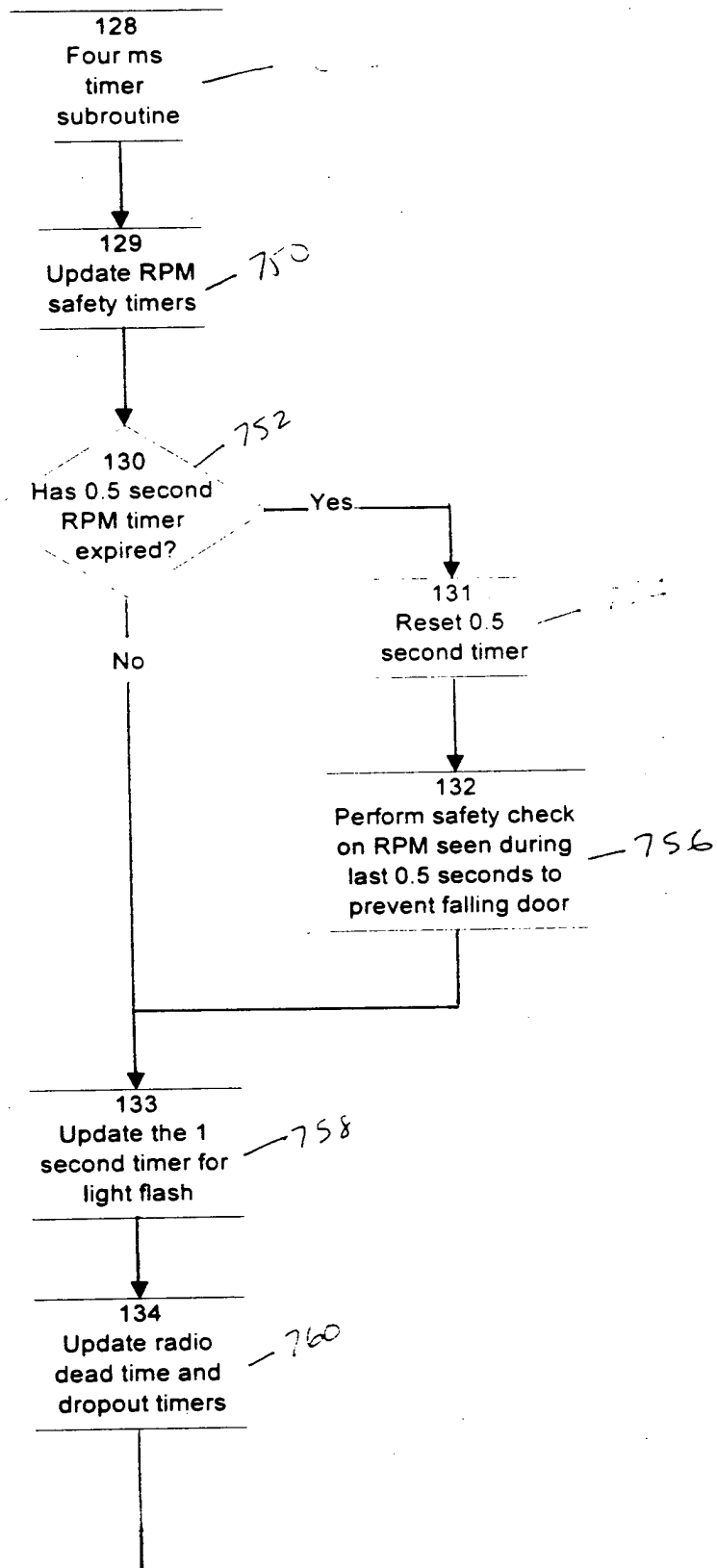
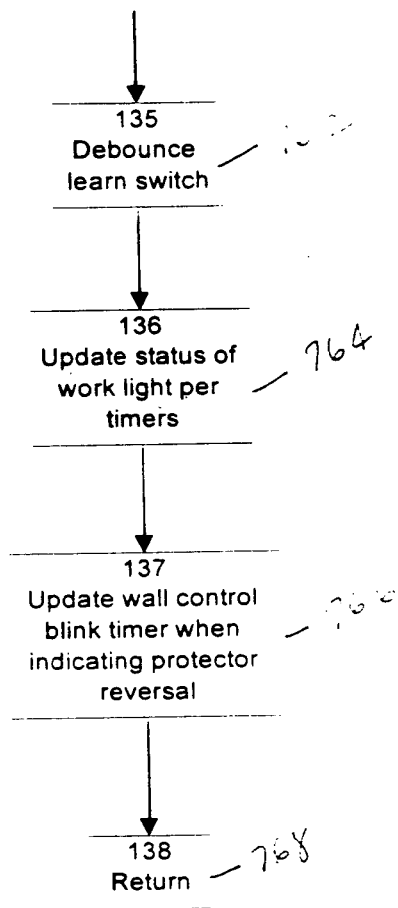


Fig. 11C

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[illegible]

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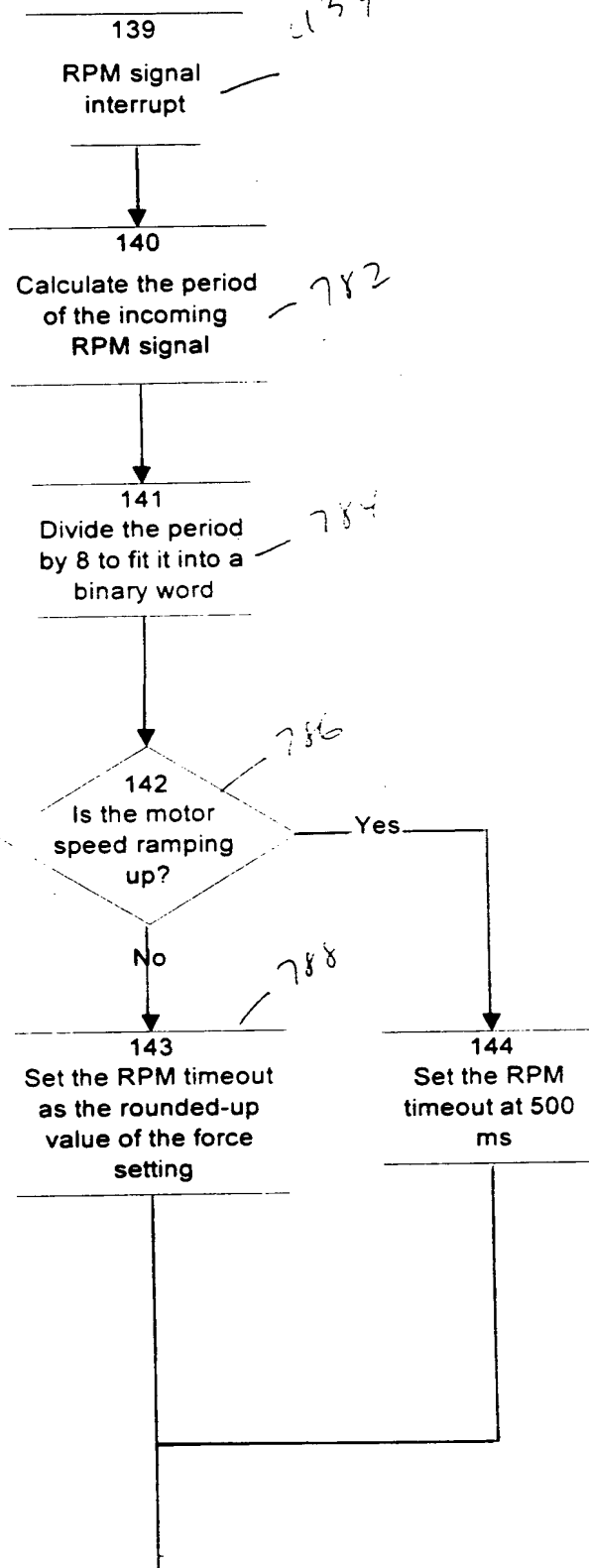


FIG. 13A

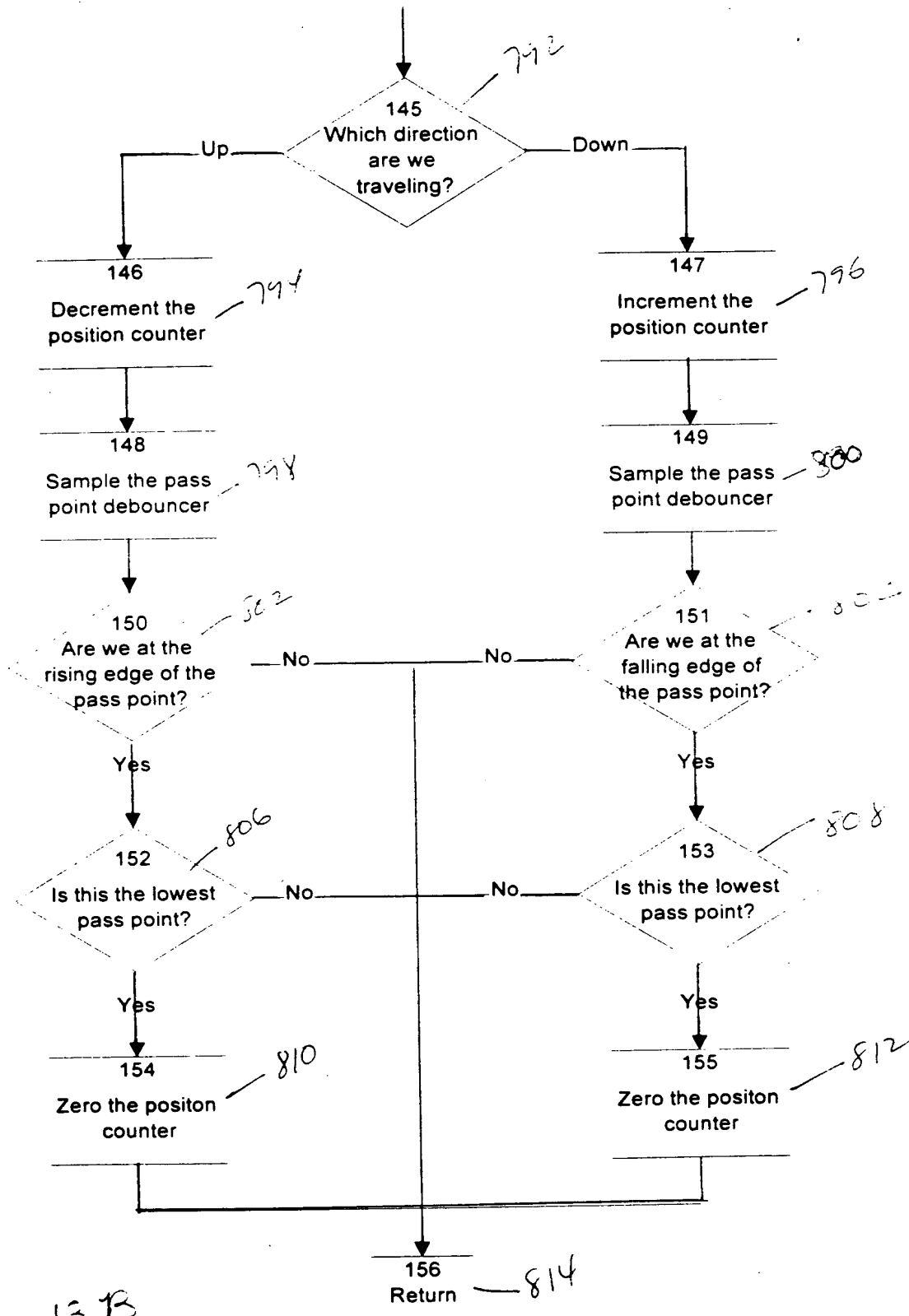


Fig. 13B

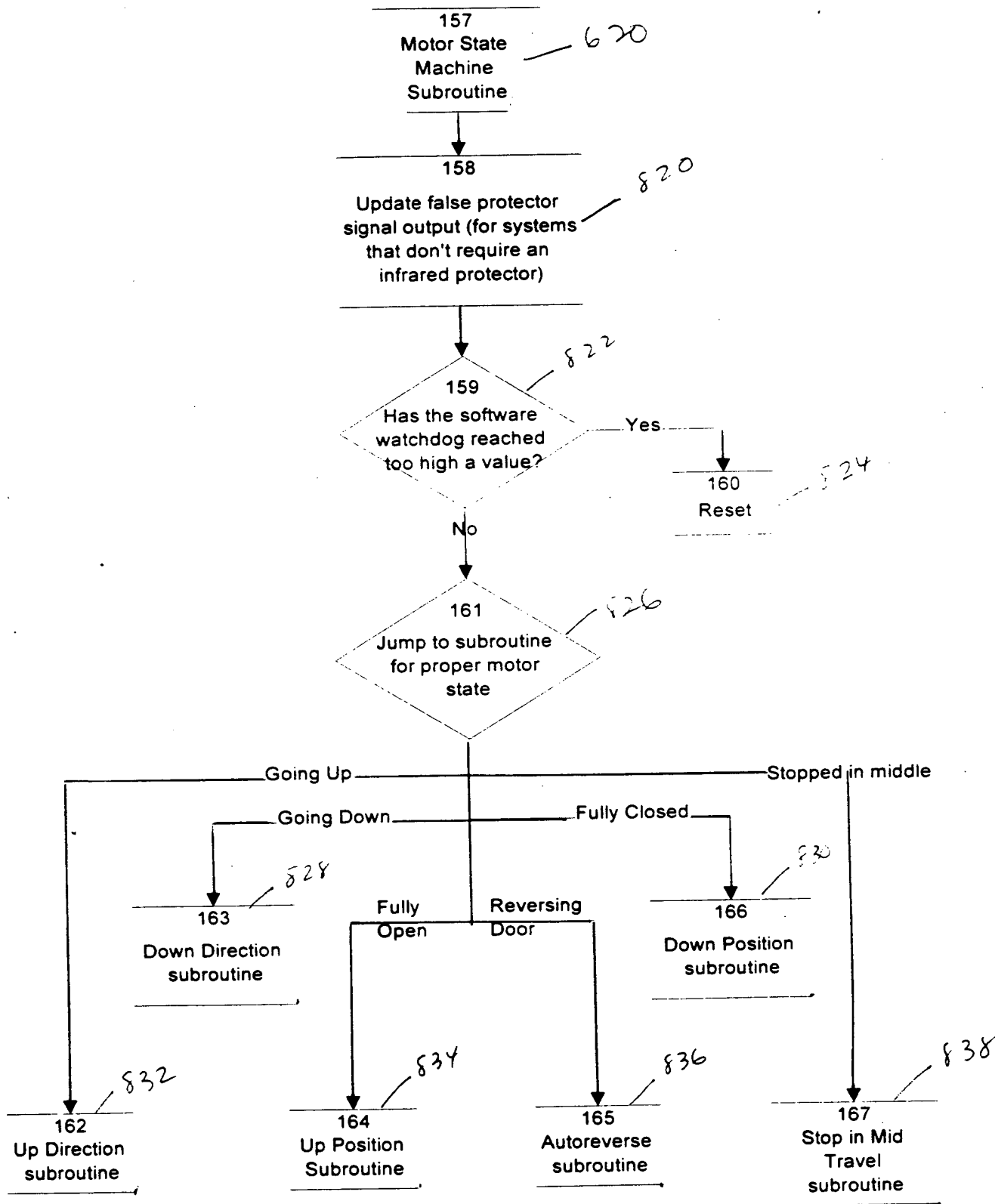


Fig. 14

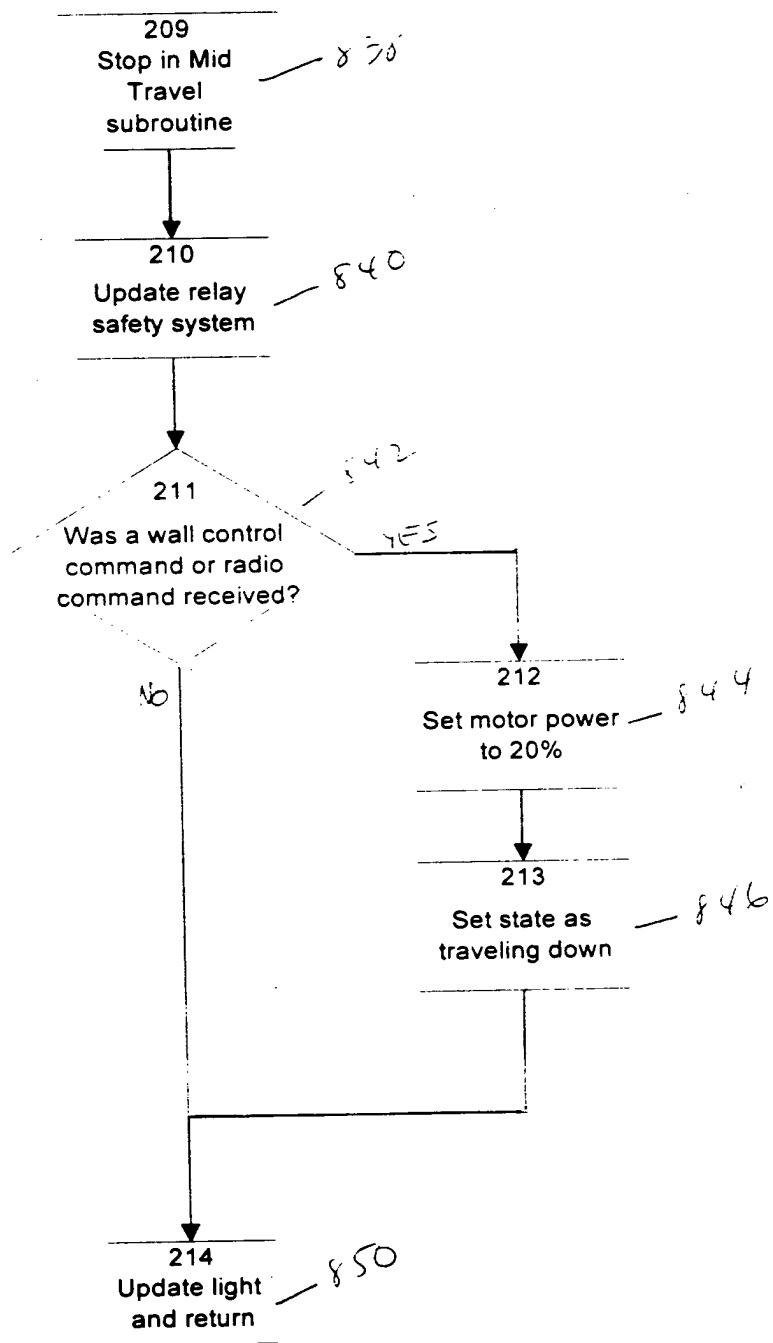


Fig. 15

000207" THE 6360

Fig. 10

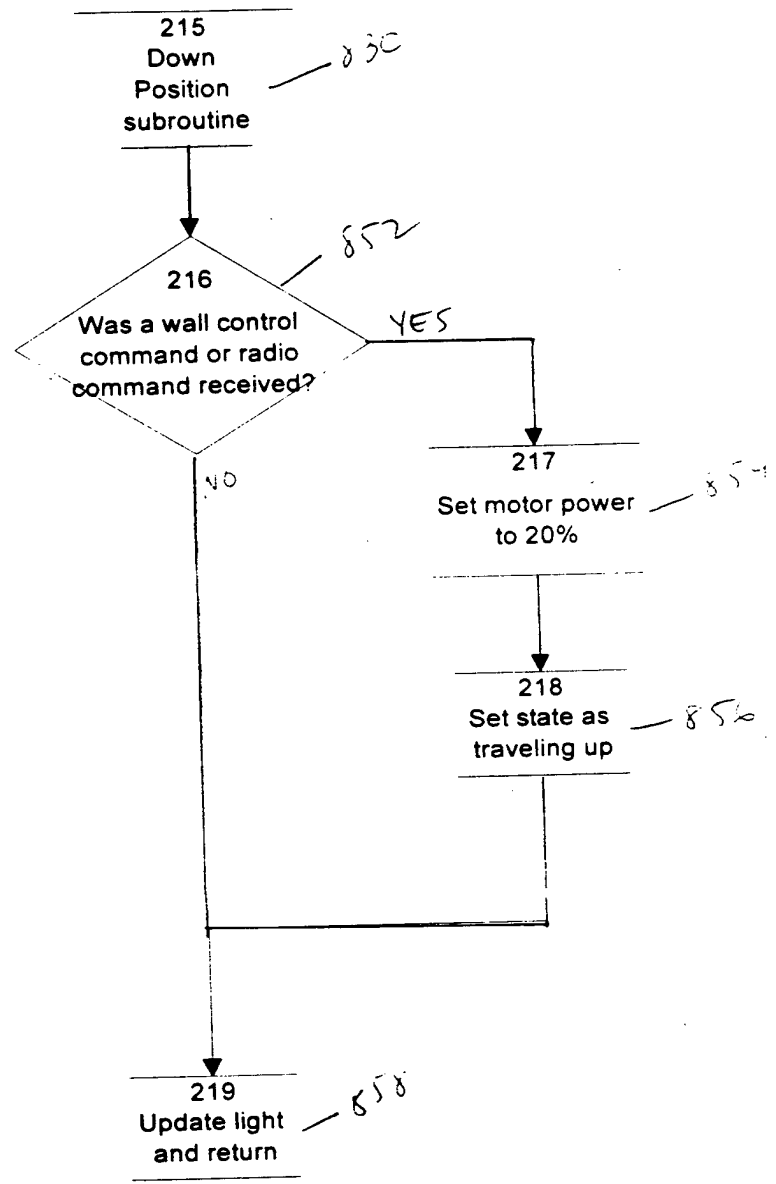
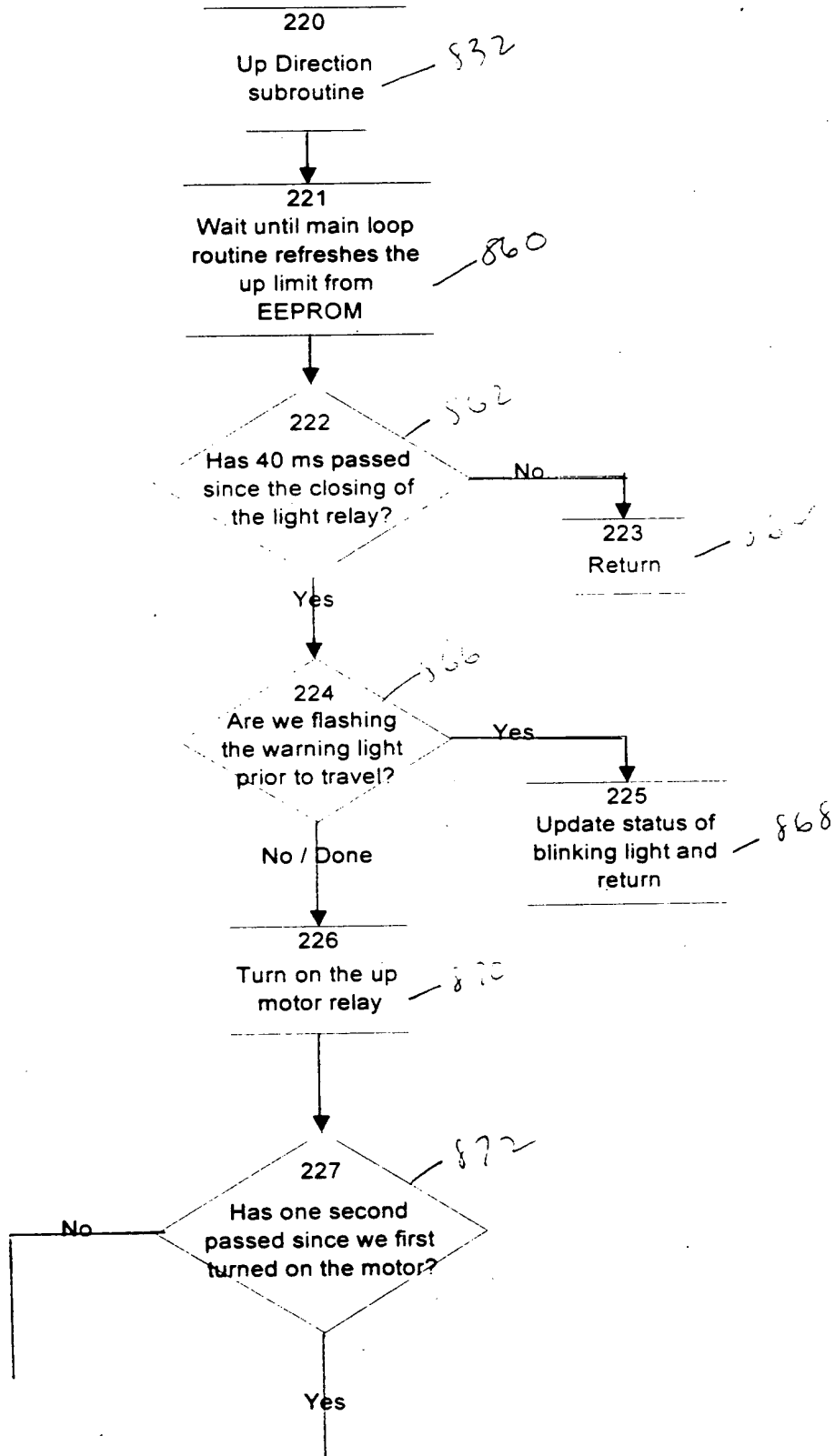
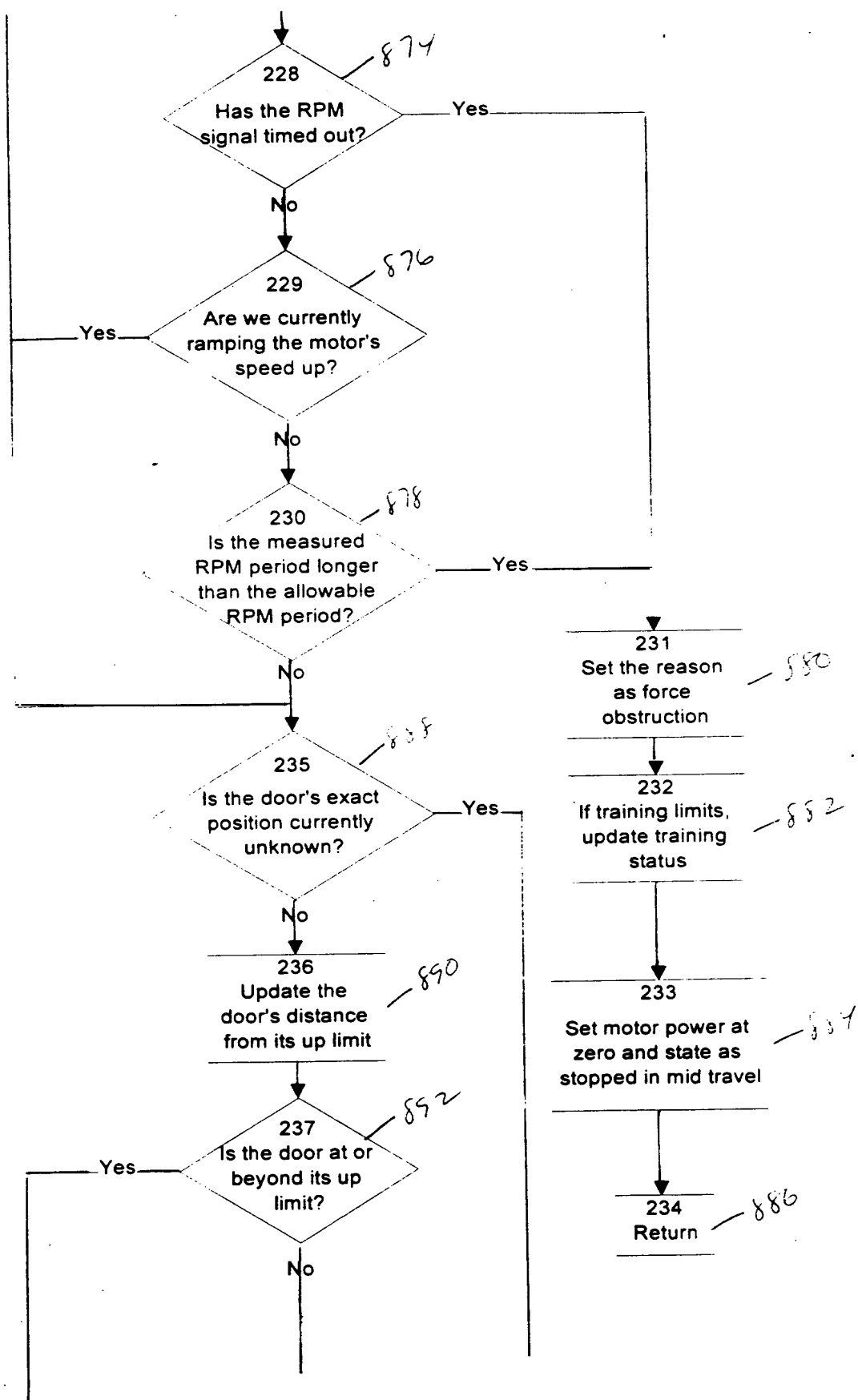
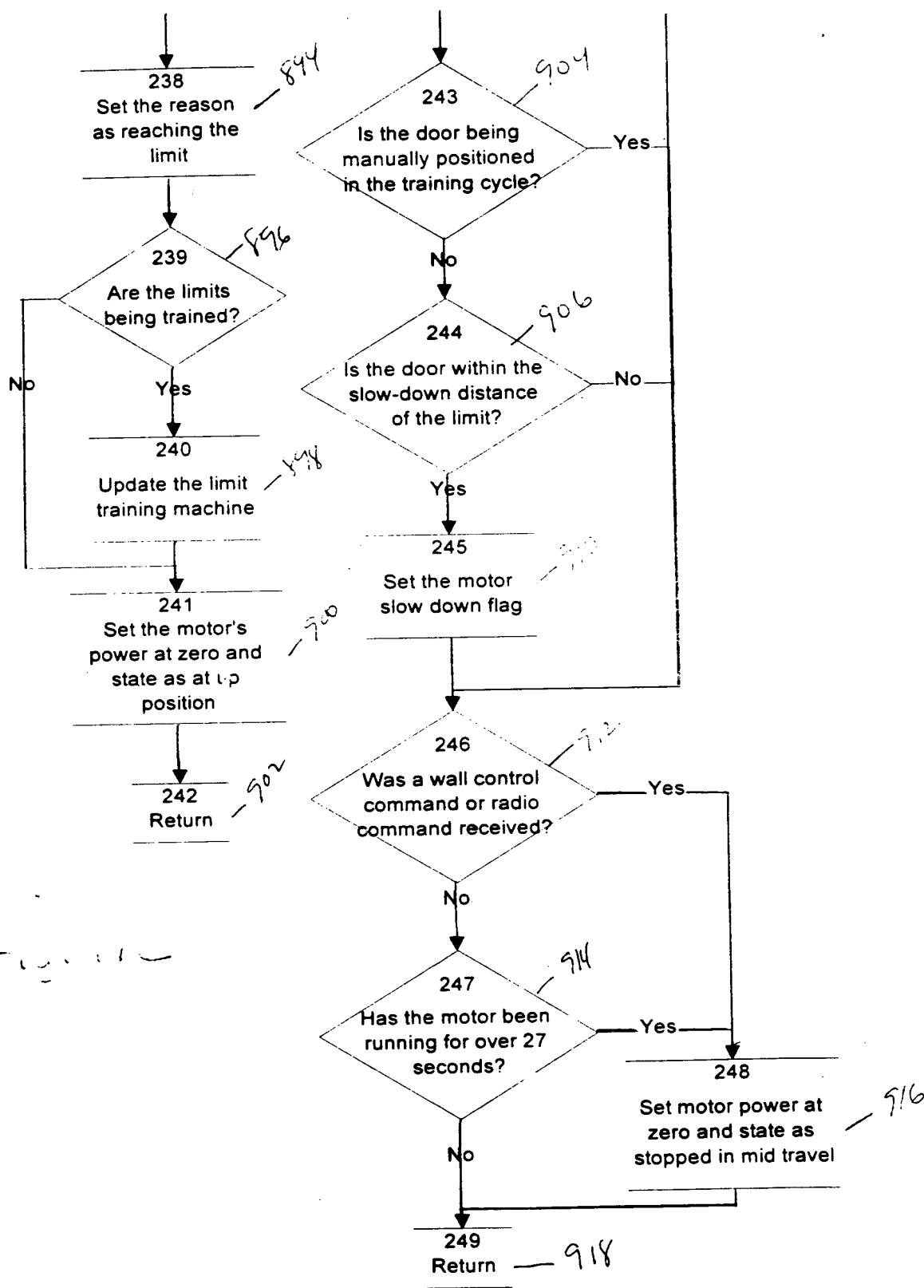


FIG. 17A







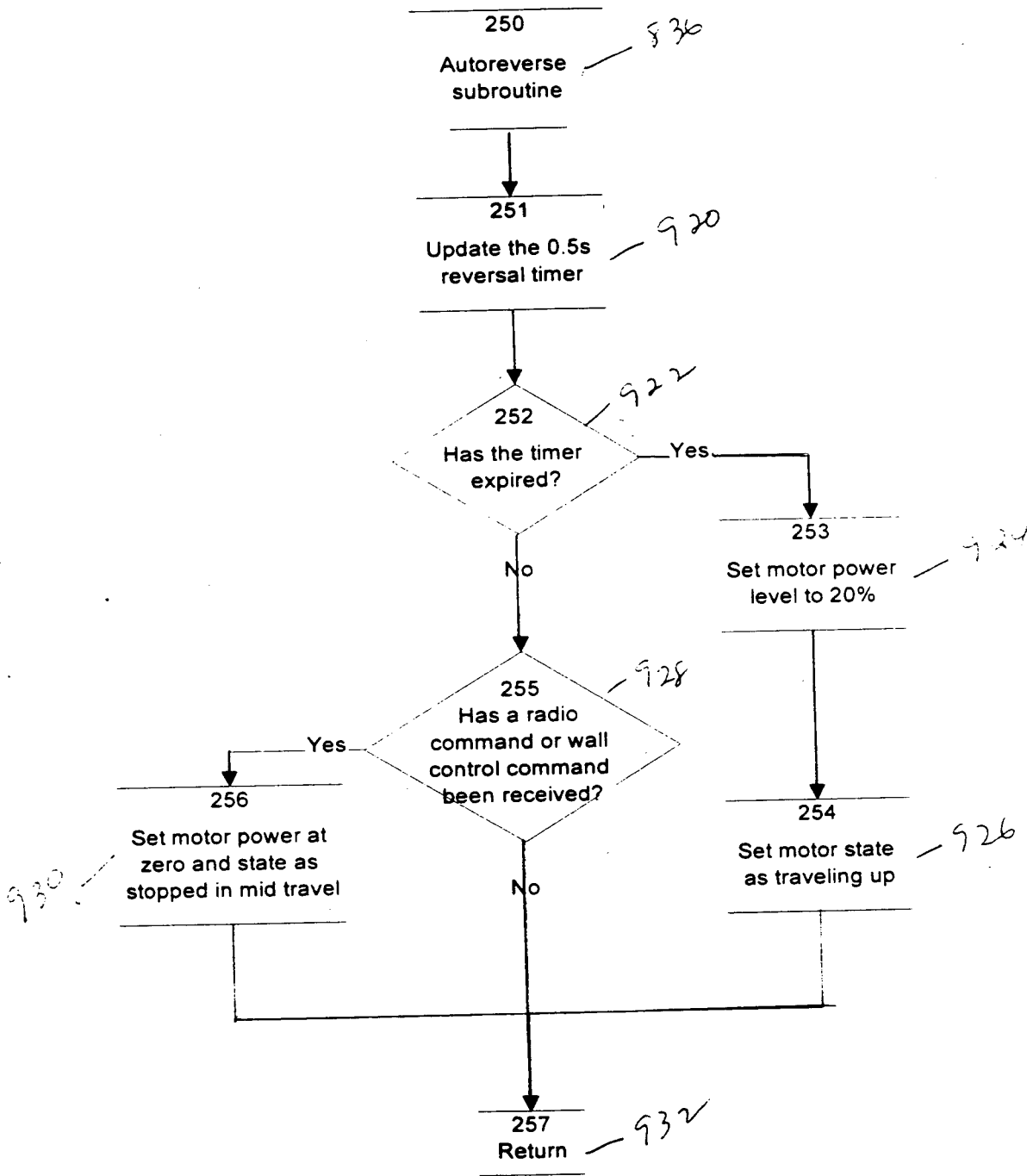


Fig. 18

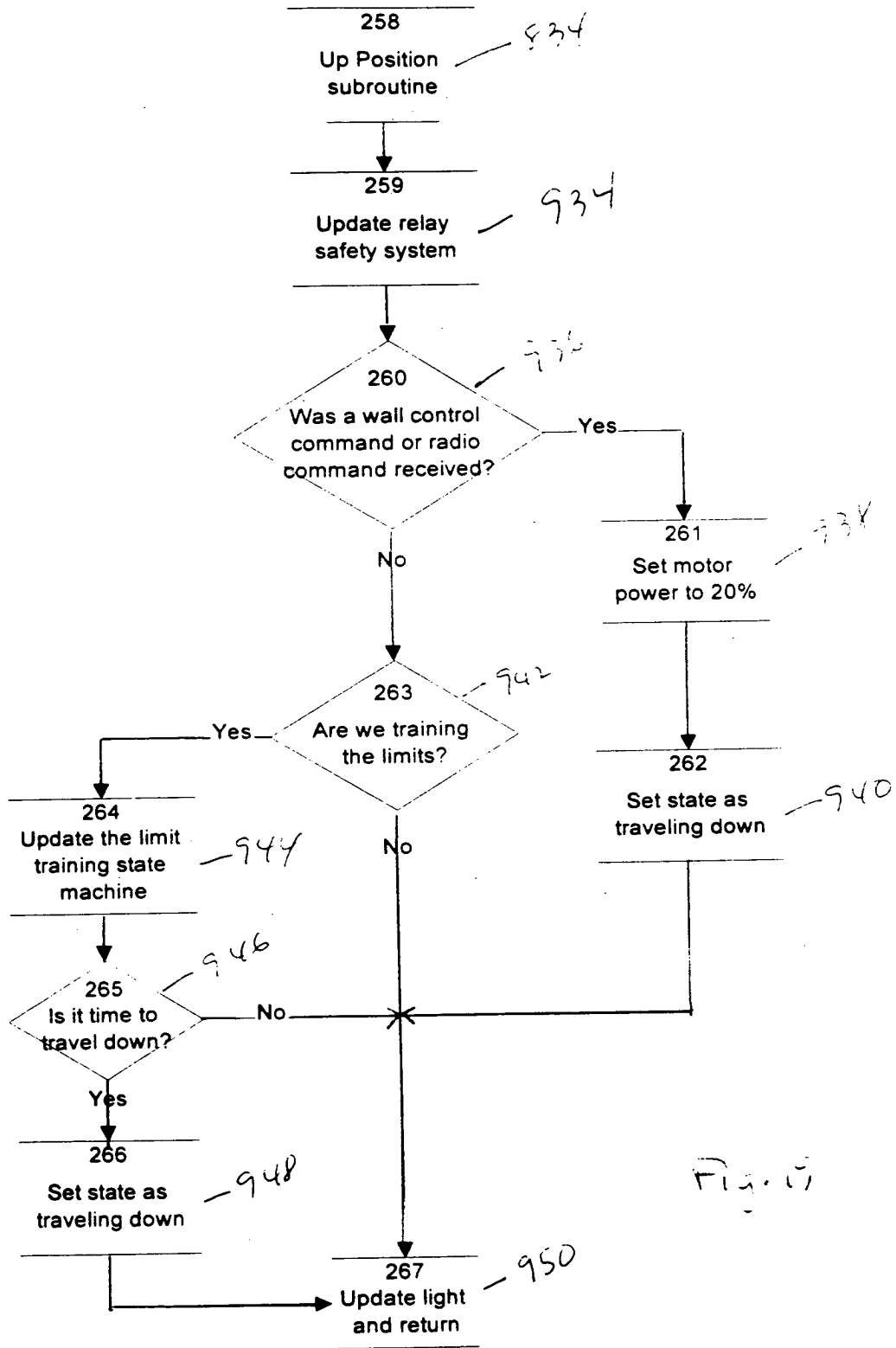


Fig. 17

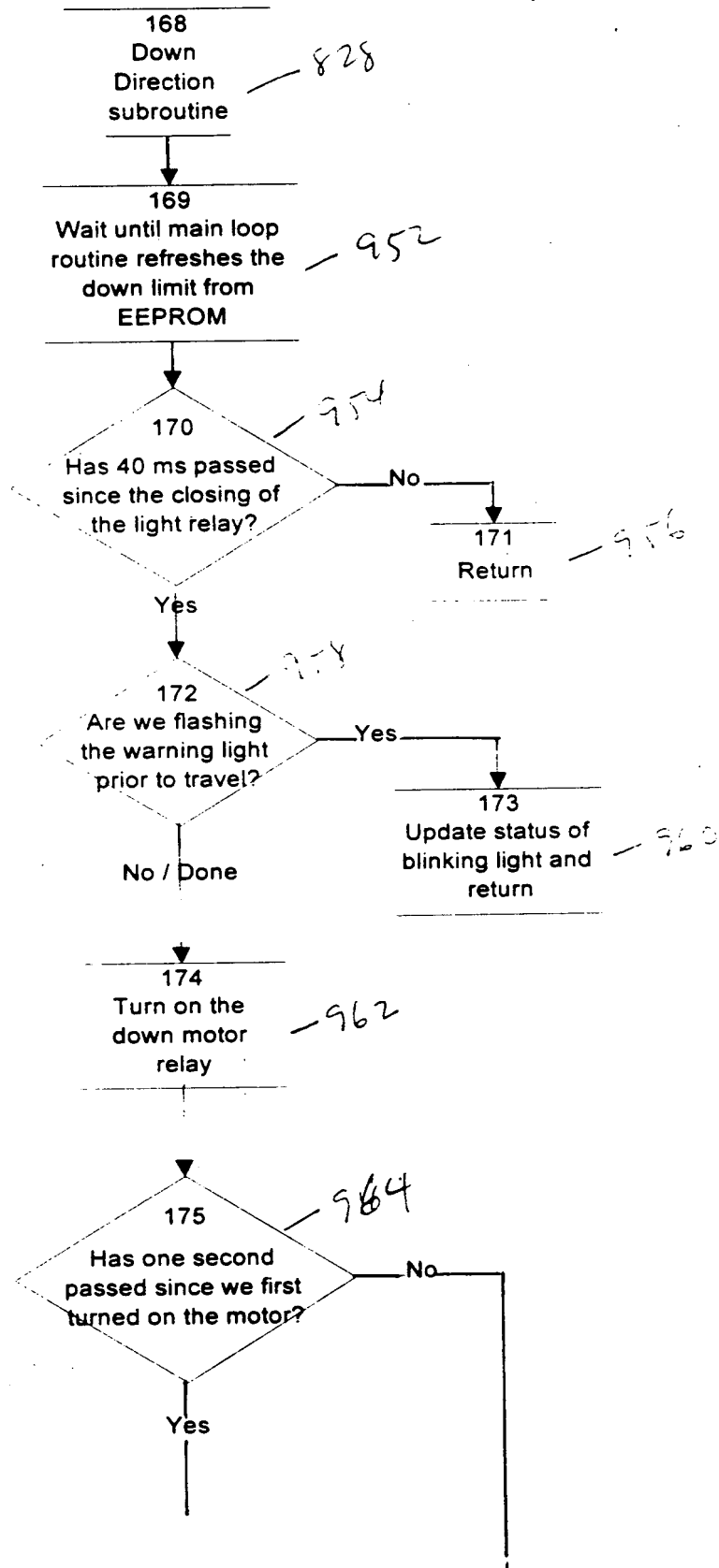


Fig. 20A

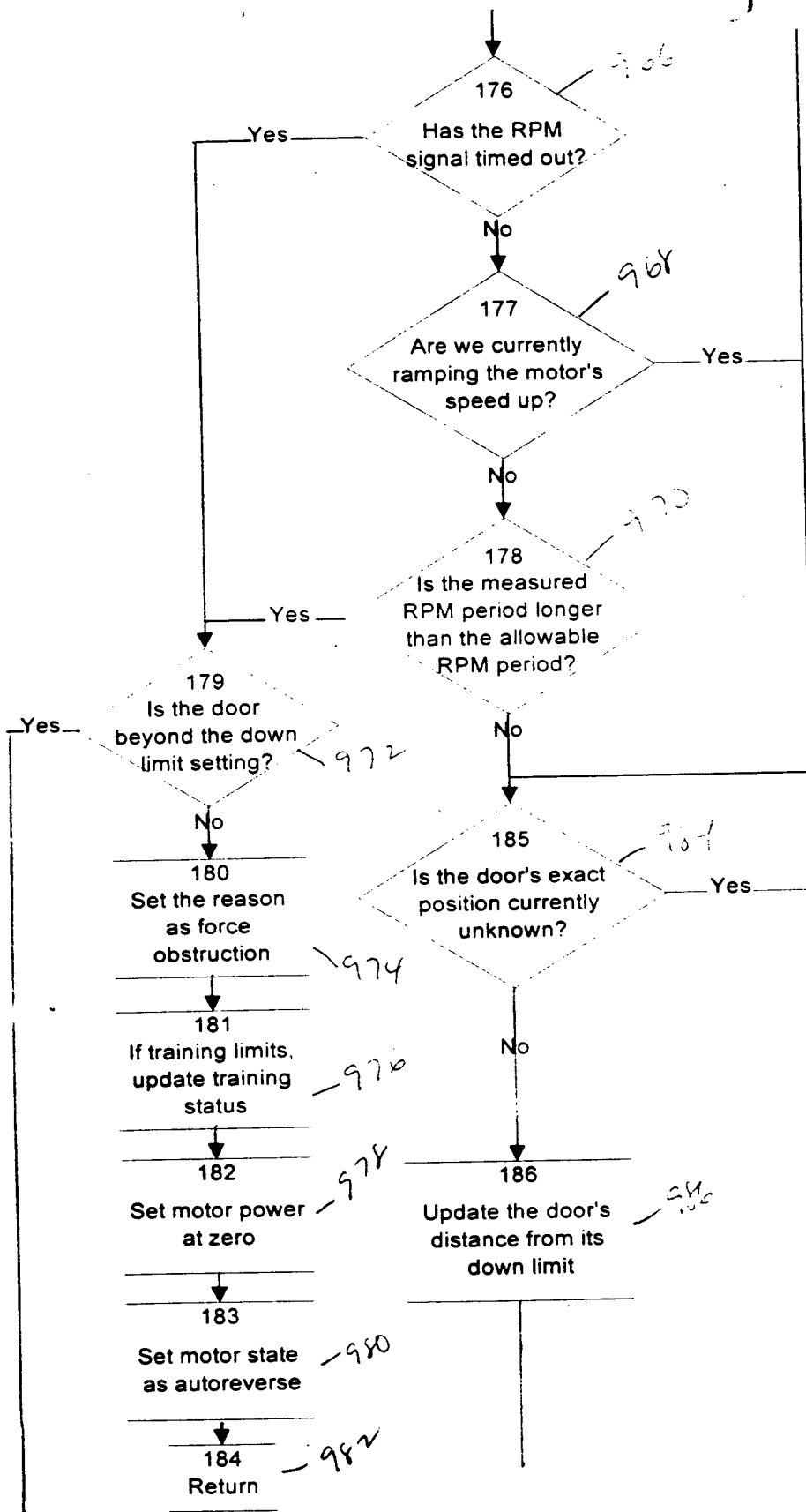
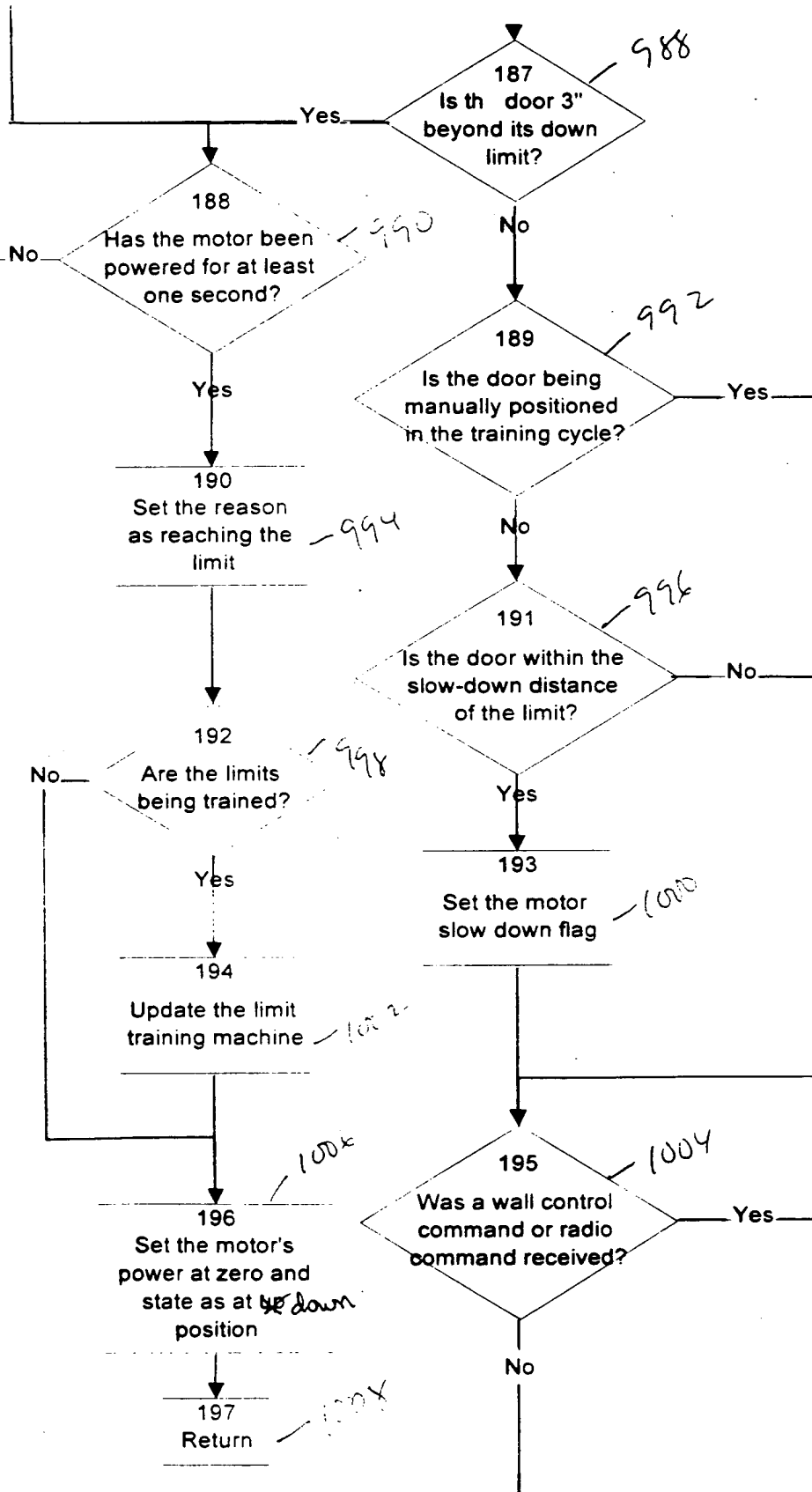


Fig. 20B



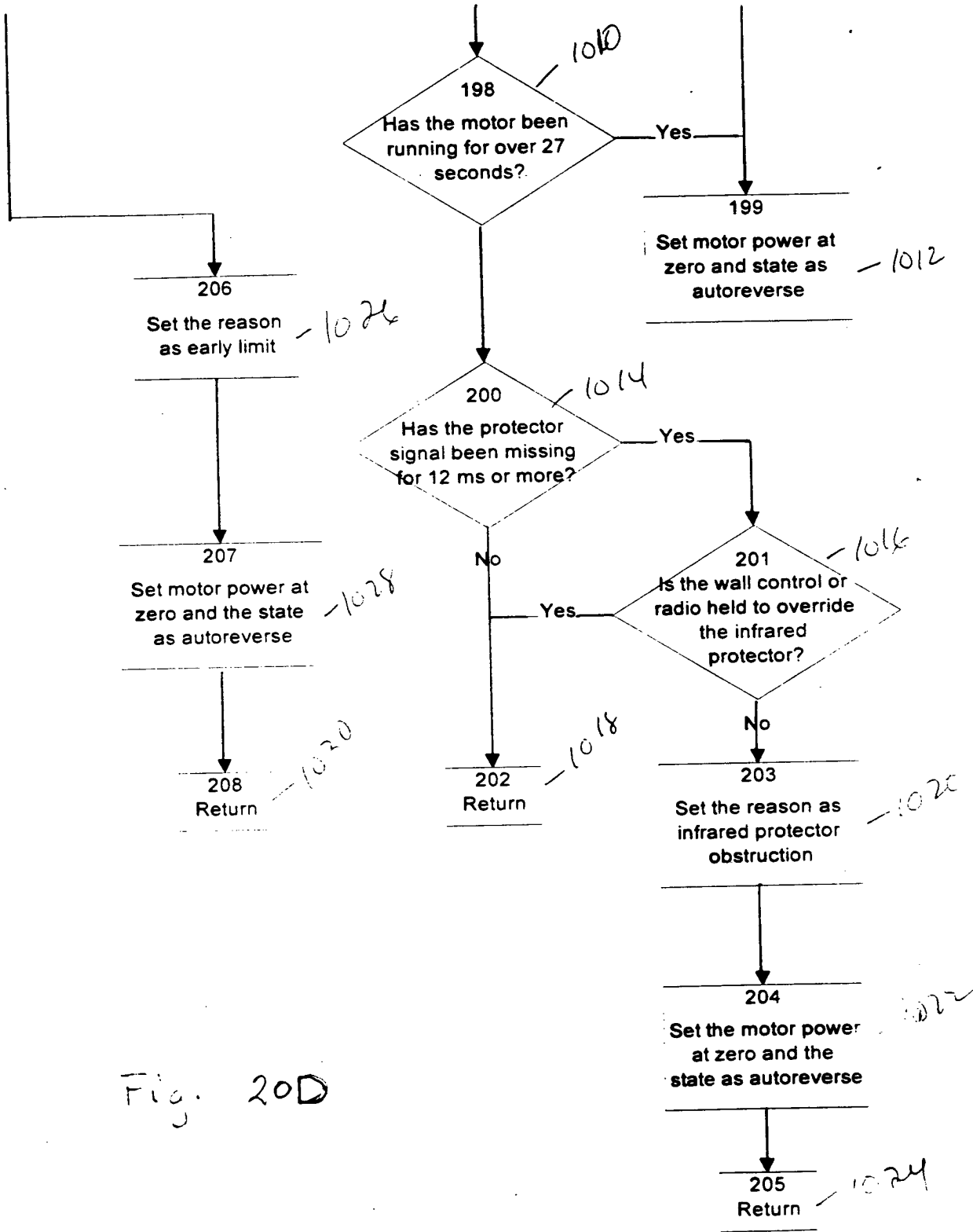
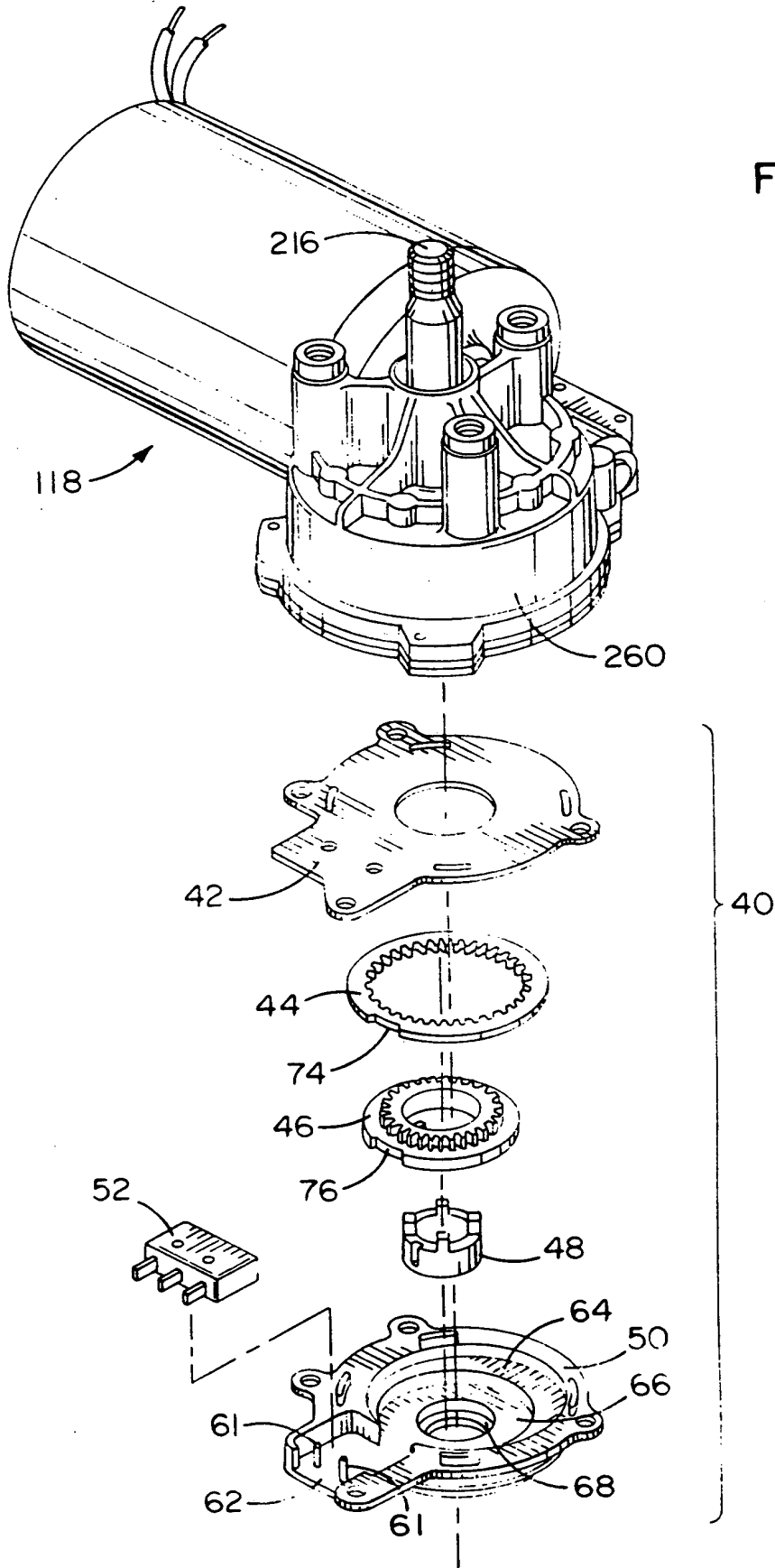


Fig. 20D

FIG. 21



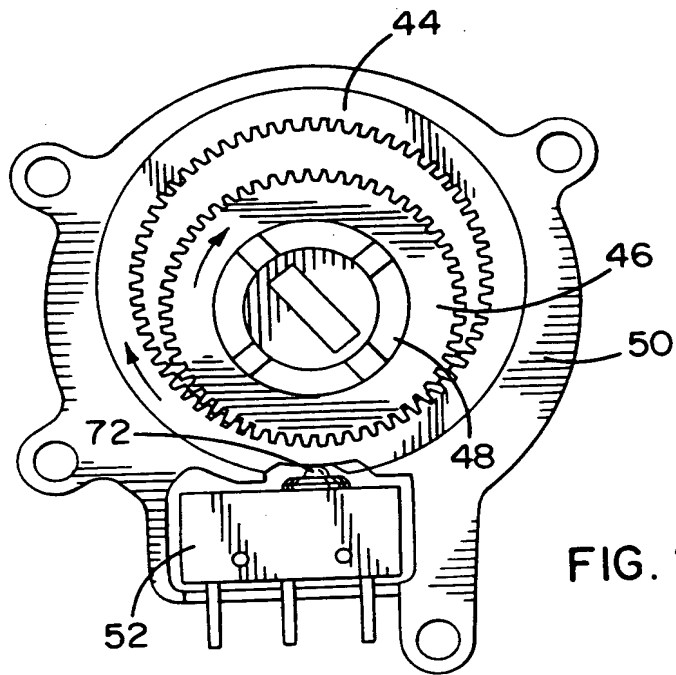


FIG. 22A

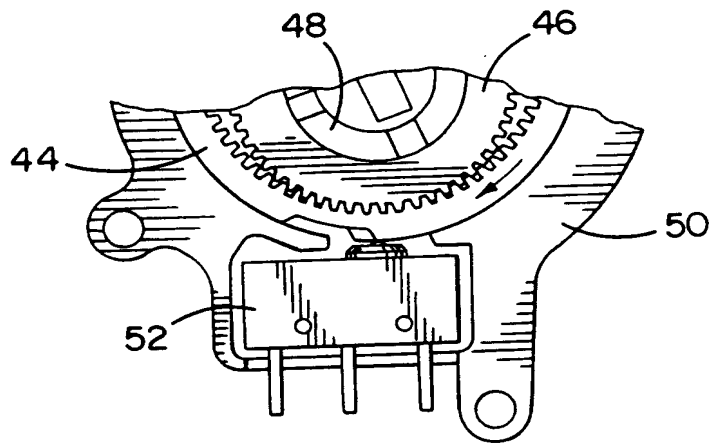


FIG. 22B